



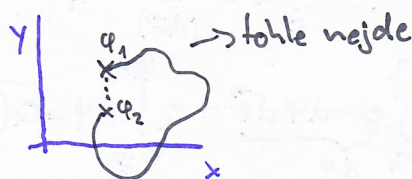


$$\frac{\Delta V \cdot \rho(\vec{r})}{|\vec{r} - \vec{r}'|} \cdot \frac{1}{4\pi\epsilon_0} = \Delta \varphi(\vec{r}) \rightarrow \varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(\vec{r}')}{R} dV' \quad \begin{array}{l} \rightarrow \text{integrační proměnná je} \\ \text{zářkovaná} \\ \vec{r} = \vec{r}' \end{array}$$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}') \cdot \vec{R}}{R^3} dV$$

→ vektor el. intenzity je všude spojitý a má všude derivaci

$$E = -\text{grad } \varphi \quad \varphi' = \varphi + C \quad \varphi \text{ je spojitý}$$



Práce elektrických sil

$$\vec{W}_E = \int_{r_1}^{r_2} \vec{E} d\vec{l} = - \int_{r_1}^{r_2} \text{grad } \varphi d\vec{l} = - \int_{r_1}^{r_2} d\varphi = \varphi(r_1) - \varphi(r_2)$$

totalní diferenciál:

$$\frac{\partial \varphi}{\partial x} dx + \frac{\partial \varphi}{\partial y} dy + \frac{\partial \varphi}{\partial z} dz$$

možná  $\vec{W}_E$

$$E_x dx + E_y dy + E_z dz$$

totalní diferenciál  $d\varphi$

$d\varphi = 0$  ekvipotenciální plocha

$E$  je kolmé na ekvipotenciální plochu

$$\vec{F}_E = -Q \int d\varphi = Q(\varphi_1 - \varphi_2)$$

$$U_m = \int_{r_1}^{r_2} d\varphi \Rightarrow \text{napětí [V] - volt}$$

Souvislost potenciál ↔ int. energie

$$W_Q = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N \frac{Q \cdot Q_i}{R_i} \quad \begin{array}{l} Q \Rightarrow \\ Q_i \cdot \vec{r}_i \end{array} \quad \begin{array}{l} \text{interakční} \\ \vec{R}_i = \vec{r} - \vec{r}_i \end{array}$$

$$W_Q = Q \cdot \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N \frac{Q_i}{R_i}$$

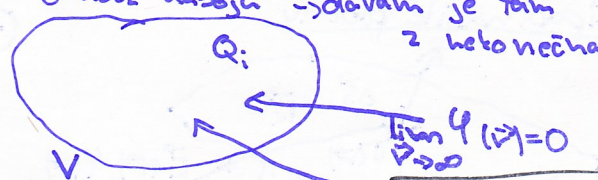
$$W_Q = Q \cdot \varphi(\vec{r})$$

Interakční energie soustavy nábojů:

$$W = \frac{1}{8\pi\epsilon_0} \sum_{i=1}^N \sum_{j=1, j \neq i}^N \frac{Q_i Q_j}{R_{ij}}$$

$$W = \frac{1}{2} \sum_{i=1}^N Q_i \varphi_i$$

obláček nábojů → dávám je tam z nekonečna



$$Q_i \varphi(\vec{r}_i) = -Q_i \int_{\infty}^{\vec{r}_i} \vec{E} d\vec{l}$$

Jednotky:  $\varphi, U: [V]$   
 $E: [V/m]$

Rovnovážná poloha: - labilní - stabilní



→ ekvipotenciální plochy → uprostřed musí být nenulový náboj → ale to nechci

Pouze elektrostatickými silami nemůžeme vytvořit rovnovážnou stabilní polohu (Earnshaw)

$$\text{div } \vec{E} = \frac{\rho}{\epsilon_0}$$

Kouknout na příklady na stránkách.



# Elektrostatické pole

$$\oint \vec{E} d\vec{s} = \frac{Q}{\epsilon_0} \quad (\text{Gaussův zákon}) \rightarrow \text{nemusi být konzerv.} \quad \boxed{\text{IV}}$$

$$\oint \vec{E} d\vec{l} = 0 \rightarrow \text{musím přidat tot. elektro stat. pole je konzervativní}$$

$$\hookrightarrow \text{rot } \vec{E} = 0 \Rightarrow \text{je konzervativní}$$

$$\vec{E}(\vec{r}) = -\nabla \varphi(\vec{r}) \quad \varphi(\vec{r}) = \varphi(\vec{r}) + C \quad \vec{E} = -\text{grad } \varphi \quad \left. \begin{array}{l} \text{div } \vec{E} = \frac{\rho}{\epsilon_0} \\ \text{Pois. vce: } \Delta \varphi(\vec{r}) = -\frac{\rho(\vec{r})}{\epsilon_0} \end{array} \right\}$$

$$\vec{F}_E = Q \cdot \vec{E} \quad \text{práce (práce)} \quad A = -\int_{\vec{r}_1}^{\vec{r}_2} Q \cdot \vec{E} \cdot d\vec{l} \quad (\text{práce vnějších sil; elektrických by byla bez mínusu})$$

$$\hookrightarrow = \int_{\vec{r}_1}^{\vec{r}_2} Q \int \text{grad } \varphi d\vec{l} = Q \int_{\varphi(\vec{r}_1)}^{\varphi(\vec{r}_2)} d\varphi = Q[\varphi(\vec{r}_2) - \varphi(\vec{r}_1)]$$

$$W = \frac{1}{2} \sum_{i=1}^N Q_i \varphi(\vec{r}_i)$$

$$\varphi(\vec{r}) = -\int_{\infty}^{\vec{r}} \vec{E} d\vec{l}$$

$$W = \frac{1}{2} \sum_{i=1}^N Q_i \varphi_i \Leftrightarrow \frac{1}{2} \int \varphi(\vec{r}) \rho(\vec{r}) dV$$

$$W = \frac{\epsilon_0}{2} \int \varphi(\vec{r}) \Delta \varphi(\vec{r}) dV$$

$$W = \frac{\epsilon_0}{2} \left[ \int \text{div}(\varphi \nabla \varphi) dV - \int (\nabla \varphi)^2 dV \right]$$

Greenova věta:  $\oint_S f_1 \text{grad } f_2 dS = \int_V \text{div}(f_1 \text{grad } f_2) dV$

$$\nabla(f_1 \text{grad } f_2) = \text{grad } f_1 \cdot \text{grad } f_2 + f_1 \Delta f_2 \quad \text{grad } \varphi^2 + \varphi \Delta \varphi = \text{div}(\varphi \nabla \varphi)$$

$$f_1 = f_2 = \varphi$$

$$W = \frac{\epsilon_0}{2} \left[ -\int_{S \rightarrow \infty} (\varphi \nabla \varphi) d\vec{s} + \int_V E^2 dV \right]$$

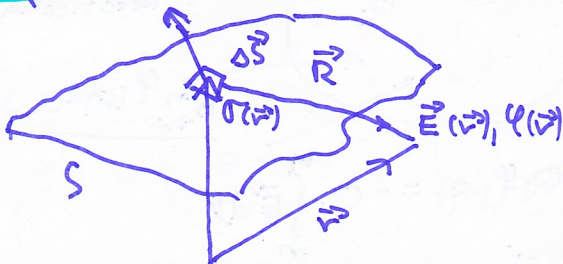
$$W = \int_V \frac{\epsilon_0 E^2}{2} dV$$

$$\left. \begin{array}{l} \text{hustota energie el. pole} \\ \epsilon_0 \vec{E} = \vec{D} \\ \epsilon_0 \vec{E} \cdot \vec{E} = \frac{\vec{E} \cdot \vec{D}}{2} \end{array} \right\}$$

$\hookrightarrow$  s nárůstem velikosti S - integrál  $\rightarrow 0$

$\hookrightarrow$  el. indukce vakua

## Případ nabitě plochy



$$\textcircled{1} \varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\sigma(\vec{r}')}{|\vec{r} - \vec{r}'|} dS \quad \hookrightarrow \frac{\sigma(\vec{r}')}{R}$$

$$\textcircled{2} E(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\sigma(\vec{r}')}{|\vec{r} - \vec{r}'|^3} (\vec{r} - \vec{r}') dS \quad \hookrightarrow \frac{\sigma(\vec{r}')}{R^2} \vec{R}$$

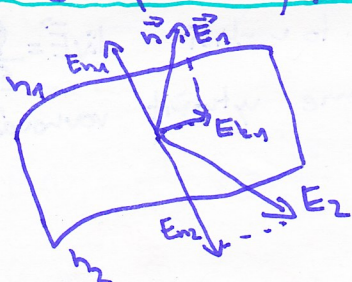
$$\boxed{\varphi(\vec{r})}$$

- 1)  $\forall$  spojitý
- 2) má derivace kromě S
- 3)  $\vec{E} = -\nabla \varphi$
- 4) E je definováno všude kromě S

$$\boxed{\sigma(\vec{r})}$$

- 1)  $\forall$  spojitý
- 2)  $\forall$  derivace
- 3)  $\vec{E} = -\nabla \varphi$
- 4) E je definováno všude

## Okrajové podmínky, na rozhraní

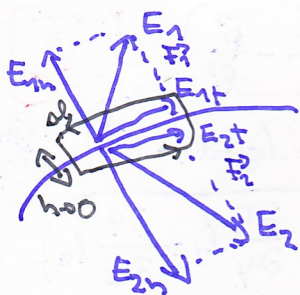


$$\Delta(\vec{n}_1 \vec{E}_1 + \vec{n}_2 \vec{E}_2) = \frac{\Delta S \cdot \sigma}{\epsilon_0}$$

$$\boxed{E_{1n} - E_{2n} = \frac{\sigma}{\epsilon_0}}$$

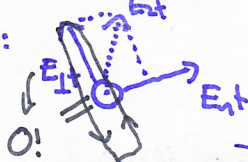
$\hookrightarrow$  nespojitost normalových složek.





$\vec{E}_1, \vec{E}_2, \vec{n} \rightarrow$  leží v jedné psoe

pohled shora:

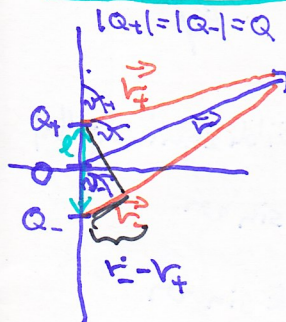
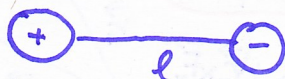


$$\oint \vec{E} d\vec{l} = 0$$

možná parda, možná ne  
-  $(\vec{E}_{2t} \text{ a } \vec{E}_{1t} \text{ jsou v přímce})$

$$\left. \begin{aligned} \Delta l \cdot \vec{F}_1 \cdot \vec{E}_{1t} + \Delta l \cdot \vec{F}_2 \cdot \vec{E}_{2t} &= 0 \\ \vec{F}_1 (\vec{E}_{1t} - \vec{E}_{2t}) &= 0 \end{aligned} \right\} \underline{\vec{E}_{1t} - \vec{E}_{2t} = 0} \rightarrow \text{spojitost tečných složek}$$

### Elektrický dipól



$$\varphi(\vec{r})$$

$$\varphi(\vec{r}) = \varphi(\vec{r}_+) + \varphi(\vec{r}_-) = \frac{1}{4\pi\epsilon_0} Q \left( \frac{1}{r_+} - \frac{1}{r_-} \right) = \frac{1}{4\pi\epsilon_0} Q \frac{r_- - r_+}{r_+ r_-} =$$

$$r \gg l$$

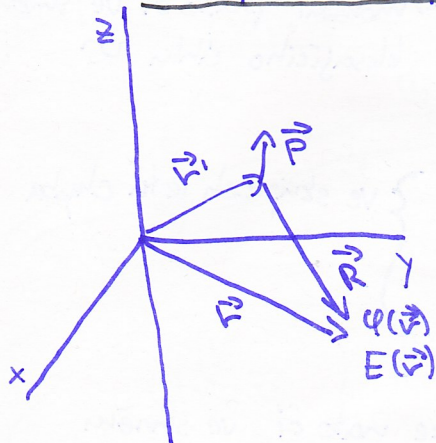
$$r_+ \approx r_- \approx r$$

$$= \frac{1}{4\pi\epsilon_0} Q \frac{l \cdot \cos \alpha}{r^2}$$

$$\boxed{\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} Q \frac{l \cos \alpha}{r^2} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{r}}{r^3}}$$

$\vec{p}$  - el. dipól. moment

Bodový elektrický dipól:  $l \rightarrow 0$ ;  $Q \rightarrow \infty$ ;  $p = \text{konst.}$



$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{R}}{R^3}$$

$$\varphi(\vec{r}), \vec{E}(\vec{r}), F, \vec{M}, W_p$$

$$\vec{E}(\vec{r}) = -\nabla \left( \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{R}}{R^3} \right)$$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left( -(\vec{p} \cdot \nabla) \frac{\vec{R}}{R^3} \right)$$

$$\vec{R} = (x, y, z) \quad R^3 = (x^2 + y^2 + z^2)^{3/2}$$

$$\nabla(\vec{V}_1 \vec{V}_2) = (\vec{V}_1 \nabla) \vec{V}_2 + (\vec{V}_2 \nabla) \vec{V}_1 + \vec{V}_1 \times \text{rot} \vec{V}_2 + \vec{V}_2 \times \text{rot} \vec{V}_1$$

$\vec{V}_1$ :  $\vec{p}$  - kolm. vektor

$$\vec{V}_2 = \frac{\vec{R}}{R^3}$$

$$-(\vec{p} \cdot \nabla) \frac{\vec{R}}{R^3} = p_x \frac{\partial}{\partial x} \frac{\vec{R}}{R^3} + p_y \frac{\partial}{\partial y} \frac{\vec{R}}{R^3} + p_z \frac{\partial}{\partial z} \frac{\vec{R}}{R^3} =$$

$$= p_x \left( \frac{1}{R^3} + \frac{x \cdot (-\frac{3}{2}) \cdot 2x}{R^5} \right) + p_y \left( \frac{x \cdot (-\frac{3}{2}) \cdot 2y}{R^5} \right) + p_z \left( \frac{x \cdot (-\frac{3}{2}) \cdot 2z}{R^5} \right)$$

$$x\text{-áí složen} = \frac{p_x}{R^3} - \frac{3(p_x \cdot x + p_y \cdot y + p_z \cdot z) \cdot x}{R^5}$$

$$\rightarrow \boxed{\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[ \frac{3(\vec{p} \cdot \vec{R}) \cdot \vec{R}}{R^5} - \frac{\vec{p}}{R^3} \right]}$$

$$F = -\nabla W = (\vec{p} \cdot \nabla) \vec{E}$$

$$W = -\vec{p} \cdot \vec{E}$$

$$\vec{M} = \vec{p} \times \vec{E}$$



# Elektrický dipól

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{r}}{r^3}$$

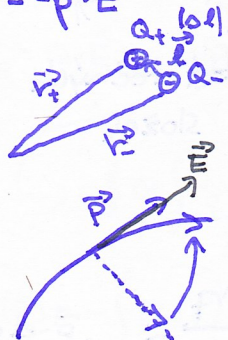
$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[ \frac{3(\vec{p} \cdot \vec{r})\vec{r}}{r^5} - \frac{\vec{p}}{r^3} \right]$$



$\vec{p}$  - dipólový moment

El. dipól v el. poli

$$W = -\vec{p} \cdot \vec{E}$$



$$W = Q_+ \varphi(\vec{r}_+) + Q_- \varphi(\vec{r}_-)$$

$$W = Q[\varphi(\vec{r}_+) - \varphi(\vec{r}_-)]$$

$$W = -Q\vec{E}\vec{l}$$

$$W = -\vec{p} \cdot \vec{E}$$

$$\varphi(\vec{r}) = \varphi(\vec{r}_-) + \left( \frac{\partial \varphi}{\partial x} l_x + \frac{\partial \varphi}{\partial y} l_y + \frac{\partial \varphi}{\partial z} l_z \right)$$

$$\vec{M} = \vec{p} \times \vec{E}$$

$$\vec{M} = \vec{r}_+ \times \vec{F}_+ + \vec{r}_- \times \vec{F}_-$$

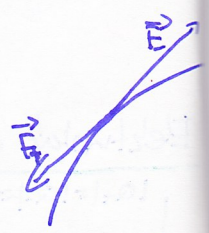
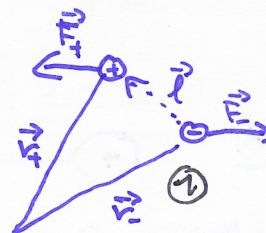
$$\vec{F}_+ = \vec{E}_+ \cdot Q_+$$

$$\vec{F}_- = \vec{E}_- \cdot Q_-$$

$\vec{E}_+ \approx \vec{E}_-$  (bodové přiblížení dipólu)

$$\vec{M} = (\vec{r}_+ - \vec{r}_-) \times Q \cdot \vec{E}$$

$$\vec{M} = Q\vec{l} \times \vec{E} = \vec{p} \times \vec{E}$$



Síla působící na dipól

$$\vec{F}(\vec{r}) = (\vec{p} \cdot \nabla) \vec{E}$$

$$\vec{F} = -\nabla W$$

$\vec{p}$  - konst. vektor

$$(\vec{F} = -\nabla(\vec{p} \cdot \vec{E})) = (\vec{p} \cdot \nabla) \vec{E} + (\vec{E} \cdot \nabla) \vec{p} + \vec{p} \times \text{rot} \vec{E} + \vec{E} \times \text{rot} \vec{p}$$

$$\vec{F} = (\vec{p} \cdot \nabla) \vec{E}$$

obrázek 1

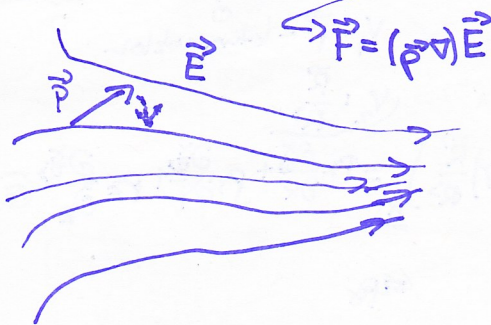
$$\vec{F} = \vec{F}_+ + \vec{F}_-$$

$$\vec{F} = Q(\vec{E}_+ - \vec{E}_-)$$

$$E(E_x, E_y, E_z)$$

$$F_x = Q \left( \frac{\partial E_x}{\partial x} l_x + \frac{\partial E_x}{\partial y} l_y + \frac{\partial E_x}{\partial z} l_z \right)$$

ve skriptech je tu chyba

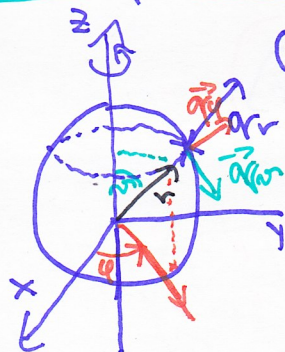


homogenní pole  $\rightarrow$  dipól se pouze natočí ve směru siločáry

nehomogenní pole  $\rightarrow$  dipól je i pole přemísťován v rámci pole

Pole dipólu ve sférické soustavě

$\rightarrow$  chci dostat  $\vec{E}(r, \varphi, \vartheta) \rightarrow$  pro dipól stačí  $\vec{E}(r, \vartheta)$



$$(r, \varphi, \vartheta)$$

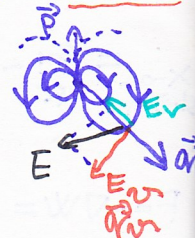
$$x = r \cdot \sin \vartheta \cdot \cos \varphi$$

$$y = r \cdot \sin \vartheta \cdot \sin \varphi$$

$$z = r \cdot \cos \vartheta$$

$$\vec{a}_r = \frac{\vec{r}}{r} \quad \vec{a}_\varphi =$$

$$\vec{a}_{\vartheta} = (\cos \vartheta, 0, -\sin \vartheta)$$



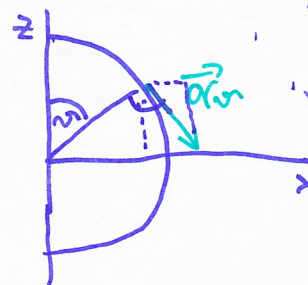
$$E_r = \vec{E} \cdot \vec{a}_r$$

$$E_\vartheta = \vec{E} \cdot \vec{a}_\vartheta$$

$$\vec{p} = (0, 0, p)$$

(D)

v rovině:



$$E_\vartheta = \frac{p}{4\pi\epsilon_0} \frac{\sin \vartheta}{r^3}$$



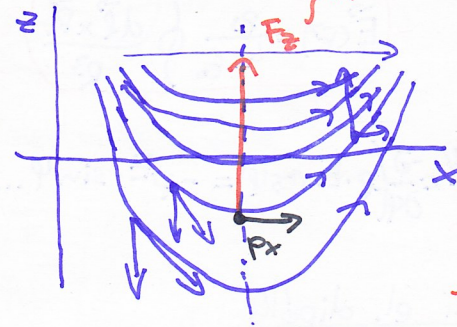
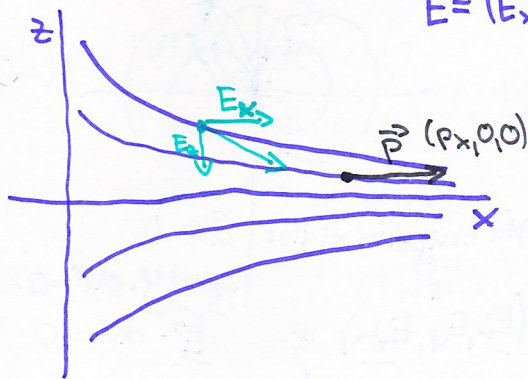
$$\frac{3(\vec{p} \cdot \vec{r}) \cdot \vec{r}}{r^5} - \frac{\vec{p} \cdot \vec{r}}{r^4} = \frac{3(\vec{p} \cdot \vec{r})r^2}{r^6} - \frac{\vec{p} \cdot \vec{r}}{r^4} = \frac{3\vec{p} \cdot \vec{r}}{r^4} - \frac{\vec{p} \cdot \vec{r}}{r^4} = \frac{2\vec{p} \cdot \vec{r}}{r^4} = \frac{2p \cdot \cos \vartheta}{r^3}$$

$$E_r = \frac{p}{2\pi\epsilon_0} \frac{\cos \vartheta}{r^3}$$

$$\vec{E} = (E_x, E_y, E_z)$$

podle ②

$$F_x = p_x \frac{\partial E_x}{\partial x}$$



$$P = (p_x, 0, 0)$$

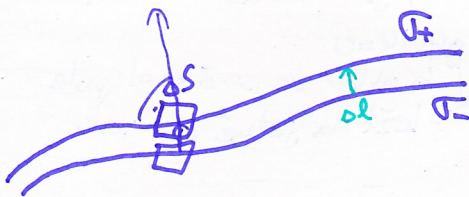
$$\vec{E} = (E_x, E_y, E_z(x))$$

$$F_z = p_z \frac{\partial E_z}{\partial x}$$

Práce elektrických sil

$$A_E = E \int_{\frac{\pi}{2}}^0 -p \sin \vartheta d\vartheta \rightarrow pE [\cos \vartheta]_{\frac{\pi}{2}}^0 = A_E$$

Elektrická dvojvrstva



$$|Q_+| = |Q_-| = Q$$

$$Q_+ = \Delta S \cdot \sigma_+$$

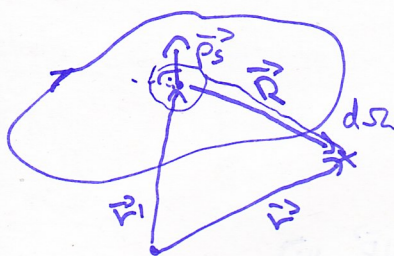
$$Q_- = \Delta S \cdot \sigma_-$$

elektrický dipólový moment

$$\vec{P}_S = \sigma \cdot \Delta \vec{r}$$

vektor plošné hustoty dipólového momentu

$$\begin{aligned} \Delta l &\rightarrow 0 \\ \sigma &\rightarrow \infty \end{aligned}$$



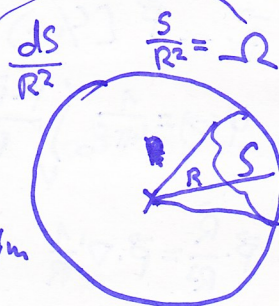
$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\vec{P}_S \cdot \vec{R}}{R^3} dS$$

pro  $\vec{P}_S = \text{konst.}$

$$\varphi(\vec{r}) = \frac{\vec{P}_S}{4\pi\epsilon_0} \int_S \frac{\vec{R} \cdot d\vec{S}}{R^3}$$

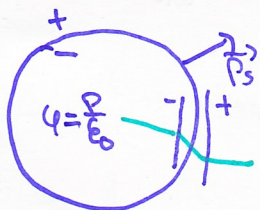
$$\frac{\vec{P}_S}{P_S} = \vec{n}$$

úhel, pod kterým vidím S.



$$\frac{\vec{R}}{R} \frac{dS}{R^2}$$

$$\varphi(\vec{r}) = \frac{P_S}{4\pi\epsilon_0} \int d\Omega$$



$\varphi = 0$   $\rightarrow$  není složka změny potenciálu, máme dvojvrstvu  $\rightarrow$  není problém

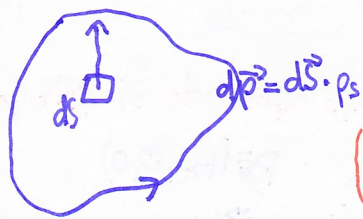


# Nábojová dvojice

$p \dots [C \cdot m]$

$\vec{p}_s \dots [C \cdot m]$

$$\varphi(\vec{r}) = \frac{p_s}{4\pi\epsilon_0} \int \frac{d\Omega}{R^2}$$



$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \left( \frac{\vec{p}_s \cdot \vec{R}}{R^5} \vec{R} - \frac{\vec{p}_s}{R^3} \right) d\Omega$$

$$\vec{E}(\vec{r}) = \frac{p_s}{4\pi\epsilon_0} \oint \frac{d\vec{\ell} \times \vec{R}}{R^3}$$

$$\vec{F} = -\nabla W \dots = -\frac{\partial W}{\partial \varphi} = -\frac{\partial}{\partial \varphi} (p \cdot E \cos \varphi) = -p E \sin \varphi \dots \vec{M}_\varphi$$

## Objemové rozložení el. dipólů

el. moment soustavy nábojů:  $Q_i, i=1, \dots, N$

$$\vec{p} = \sum_i \vec{r}_i Q_i$$

$$\rho = \sum_i (\vec{r}_i + \vec{r}_0) Q_i$$

$$|\vec{p}_+(\vec{r})| = |\vec{p}_-(\vec{r})|$$

$$\vec{p}_s \dots \vec{p}_v = \vec{p}(\vec{r}) \cdot \Delta \vec{\ell}$$

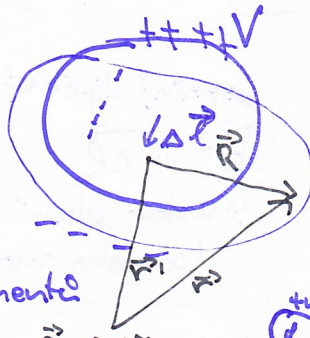
objemová hustota dip. momentů

$$\vec{p}_v \dots \vec{p} [C \cdot m^2]$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\vec{p} \cdot \vec{R}}{R^3} dV$$

$$\vec{p} \cdot \frac{\vec{R}}{R^3} = \vec{p} \cdot \nabla \frac{1}{R}$$

$$\vec{p} \cdot \nabla \frac{1}{R} = \nabla \cdot \left( \frac{1}{R} \vec{p} \right) - \frac{1}{R} \nabla \cdot \vec{p}$$



$$\lim_{\Delta V \rightarrow 0} \frac{\Delta \vec{p}}{\Delta V} = \vec{p}$$

$$\Delta \vec{p} = \vec{p} \cdot \Delta V$$

$$\nabla \cdot (s \vec{V}) = \vec{V} \cdot \nabla s + s \nabla \cdot \vec{V}$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[ \int_V \text{div} \left( \frac{\vec{p}}{R} \right) dV - \int_V \frac{\text{div} \vec{p}}{R} dV \right]$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[ \oint_S \frac{\vec{p} \cdot \vec{n}}{R} dS + \int_V \frac{-\text{div} \vec{p}}{R} dV \right]$$

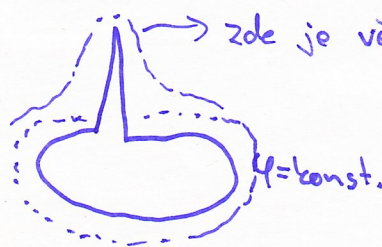
$$(d\vec{s} = \vec{n} \cdot dS)$$

$$\varphi = \vec{p} \cdot \vec{n}$$

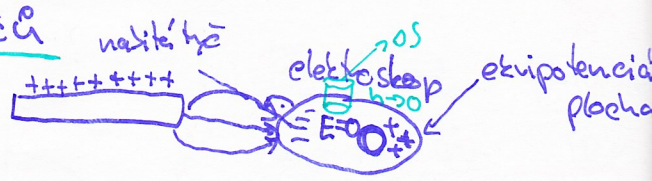
$$\rho_p = -\text{div} \vec{p}$$

## Elektrostatické pole nabitých vodičů

Vodič  $\rightarrow$  objekt, volně nositelné náboje



zde je větší intenzita elektrického pole

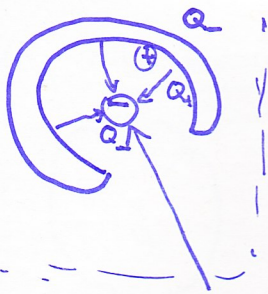


$$\frac{\sigma \Delta S}{\epsilon_0} = \Delta S \cdot E$$

$$\frac{\sigma}{\epsilon_0} = E$$

Coulombova věta





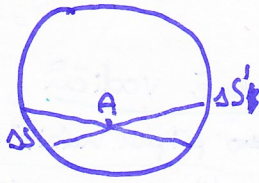
Van der Graaff generator



$\square DU \rightarrow$

ověření Coulombova zákona  
 $\hookrightarrow$  knize

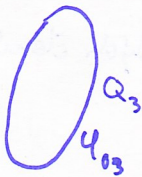
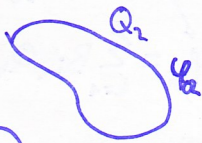
Cavendish  $\rightarrow$



**VII**

Hustota siločiviek je úměrná intenzitě elektrického pole.

Základní úloha elektrostatiky.



$$Q_1 = \epsilon_0 \oint \nabla \phi d\vec{S}$$

$Q_i$   
 $\sigma_i(\vec{r})$

$$\Delta \phi = -\frac{\rho}{\epsilon_0}$$

(\*)  $\Delta \phi = 0$  L.R. (Laplaceova rovnice)

$\phi_{oi}$ , tělesu v konečném objemu  $\rightarrow \lim_{r \rightarrow \infty} \phi(\vec{r}) = 0$

Jednoznačnost řešení (\*)  $\rightarrow$  Důkaz:  $\phi_1(\vec{r}), \phi_2(\vec{r})$

Thomsonova věta

$\phi_1 - \phi_2$ , obrazová podmínka  $\phi_i = 0$

nemůže mít extrém v prostoru bez náboje

$$\Rightarrow \phi_1 = \phi_2$$

Metoda elektrostatického zobrazení



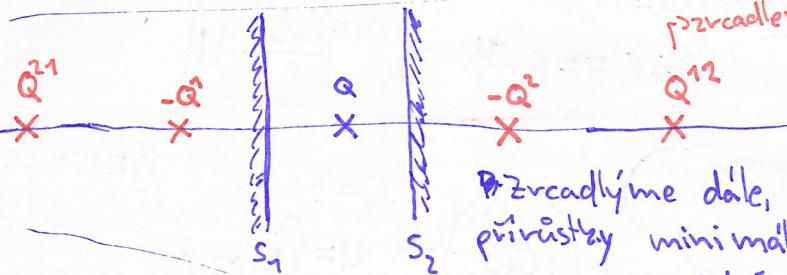
$\vec{F} = ?$   
 $\vec{E} = ?$   
 $\phi = ?$

$$\nabla = \epsilon_0 \cdot \vec{E}$$

$$\iint \sigma_m d\vec{S} = -Q$$

$\rightarrow$  Přimyslím si náboj  $-Q$ ; náboj se "rozlije" do vodiče  
 plochy

$\Delta \phi = 0 \rightarrow$  obrazová podmínka

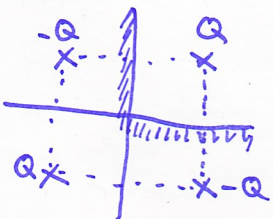


zrcadlený  $-Q^1$  podle  $S_1$

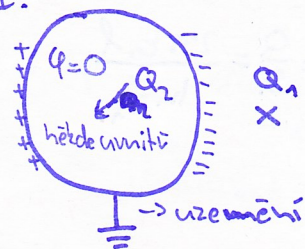
Zrcadlíme dále, dokud nejsou přírůstky minimální. Ideální pro numerické řešení

a)  $Q_2 \neq 0$

b) není uzemnění  $\rightarrow Q_2 = 0$



I.



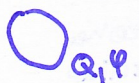
$\rightarrow$  uzemnění



# Kapacita, kondenzátor

$$\frac{Q}{\varphi_0} \rightarrow \text{vlastní kapacita vodiče}$$

$$\hookrightarrow \text{Farad } \left[ \frac{C}{V} \right]$$

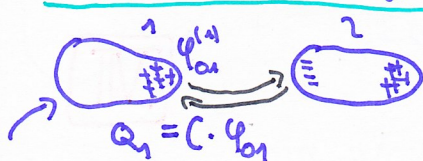


$$A \cdot Q \Rightarrow A \cdot \varphi$$

$\hookrightarrow$  konstanta

$$\frac{Q}{\varphi} = \text{konst.}$$

## Vztah mezi $Q_i$ a $\varphi_{0i}$ v soustavě vodičů



$$Q_1 = C \cdot \varphi_{01}$$

$\varphi_{02}^{(1)} \rightarrow$  pro případ nabitého tělesa 1.

$$\varphi_{01}^{(1)} = B_{11} Q_1 ; \varphi_{02}^{(1)} = B_{21} Q_1$$

$$\varphi_{01}^{(2)} = B_{12} Q_2 ; \varphi_{02}^{(2)} = B_{22} Q_2$$

$\hookrightarrow$  konst.

$B_{ik} \rightarrow$  potenciálové koeficienty

$$\varphi_{01} = \varphi_{01}^{(1)} + \varphi_{01}^{(2)} \parallel \varphi_{02} = \varphi_{02}^{(1)} + \varphi_{02}^{(2)} = B_{21} Q_1 + B_{22} Q_2$$

$$\hookrightarrow = B_{11} Q_1 + B_{12} Q_2 \quad \rightarrow \quad \varphi_{0i} = \sum_{k=1}^N B_{ik} Q_k$$

$$Q_i = \sum_{k=1}^N C_{ik} \varphi_{0k}$$

$$C_{ik} \cdot B_{kj} = \delta_{ij}$$

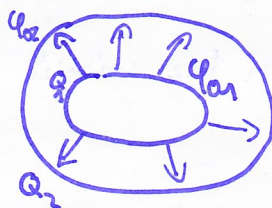
$\hookrightarrow C$  je inverzní matice vůči  $B$ .

$$\left. \begin{array}{l} B_{ik} = B_{ki} \\ C_{ik} = C_{ki} \end{array} \right\} \frac{N(N+1)}{2} \text{ nezávislých členů}$$

kapacitní koef. ....  $C_{ii}$  (kladné)  
influenční koef. ....  $C_{ik}$  (záporné)  
 $i \neq k$

$$C \leq C_{ii}$$

## Kondenzátor



$$Q_1 = -Q_2 = Q$$

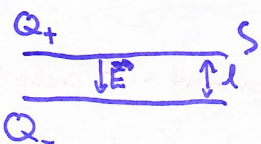
$$Q_1 = \varphi_{01} \cdot C_{11} + \varphi_{02} \cdot C_{12}$$

$$Q_2 = \varphi_{01} \cdot C_{21} + \varphi_{02} \cdot C_{22}$$

$$C = \frac{Q_1}{\varphi_{01} - \varphi_{02}}$$

$$C = \frac{Q_2}{\varphi_{02} - \varphi_{01}} = \frac{Q_1}{U}$$

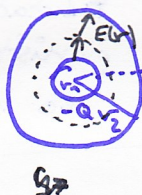
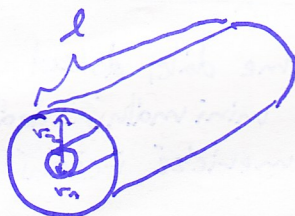
$$C = \frac{C_{11} \cdot C_{22} - C_{12} \cdot C_{21}}{C_{11} + C_{12} + C_{21} + C_{22}}$$



$$Q = \sigma \cdot S$$

$$\sigma = \epsilon_0 E = \epsilon_0 \cdot \frac{U}{l}$$

$$\left. \begin{array}{l} Q = \sigma \cdot S \\ \sigma = \epsilon_0 E = \epsilon_0 \cdot \frac{U}{l} \end{array} \right\} Q = \left( \frac{\epsilon_0 S}{l} \right) \cdot U$$



$$C = ?$$

$$U = \int_{r_1}^{r_2} E dr$$

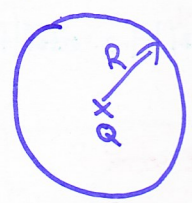
$$\oint \vec{E} d\vec{s} = \frac{Q}{\epsilon_0} = \frac{Q}{\epsilon_0}$$

$$E(r) = \frac{Q}{\epsilon_0 2\pi r l}$$

$$C = \frac{Q}{U} = \frac{2\pi \epsilon_0 l}{\ln \frac{r_2}{r_1}}$$



# Kapacita kulové plochy



$$C = 4\pi\epsilon_0 \cdot R$$

$$\varphi_{ok} = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{R}$$

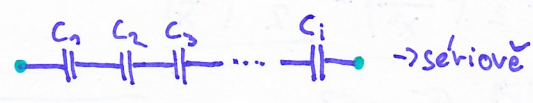
$$\lim_{r \rightarrow \infty} \varphi(r) = 0$$

$$\frac{Q}{U} = 4\pi\epsilon_0 R$$

$$\frac{Q}{U_i} = C_i \rightarrow U_i = \frac{Q}{C_i}$$

$$U = \sum U_i; C_s = \frac{Q}{U} = \frac{Q}{\sum \frac{Q}{C_i}} \Rightarrow \sum \frac{1}{C_i} = \frac{1}{C_s}$$

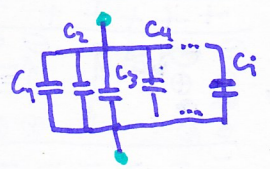
⊥ - kondenzátor



→ sériově

$$U \dots U_i$$

$$Q = Q_i$$



→ paralelně

$$U_i = U; i = 1, \dots, N$$

$$Q_i \text{ různé}; \sum Q_i = Q$$

$$C_p = \frac{Q}{U} = \frac{\sum Q_i}{U} = \sum \frac{Q_i}{U} = \sum C_i$$

## Energie vodičů v elektrostatickém poli

$C, Q', \varphi'$   
↓  
vodiče

Přivedeme malý náboj  $\Delta Q'$ :  $\Delta W = \varphi'_0 \Delta Q'$

$$W = \int_0^{Q'} \varphi'_0 \cdot dQ' = \frac{1}{C} \cdot \int_0^{Q'} Q' dQ' = \frac{1}{C} Q^2 \cdot \frac{1}{2}$$

Osamocený vodič

$$W = \frac{1}{2} \frac{Q^2}{C} = \frac{1}{2} Q \varphi_0$$

N vodičůch těles ...  $\varphi_{0i}, Q_i$

$$Q'_i = + \cdot Q_i; t \in (0, 1)$$

$$\varphi'_{0i} = + \cdot \varphi_{0i}$$

→ nezáleží na tom, v jakém pořadí tělesa náboj získala.

$$W = \sum_{i=1}^N \int_0^{Q_i} \varphi'_{0i} dQ'_i = \sum_{i=1}^N \varphi_{0i} \cdot Q_i \int_0^1 t dt = \frac{1}{2} \sum_{i=1}^N \varphi_{0i} Q_i$$

## Energie kondenzátoru

$$W = \frac{1}{2} Q (\varphi_{01} - \varphi_{02}) = \frac{1}{2} Q U$$

i-tý vodič

$$W_i = \frac{1}{2} B_{ii} Q_i^2$$

$$Q_i = \sum_{k=1}^N C_{ik} \cdot \varphi_{0k}$$

$$\varphi_{0i} = \sum_{k=1}^N B_{ik} Q_k$$

$$W = \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N C_{ik} \varphi_{0i} \varphi_{0k} = \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N B_{ik} Q_i Q_k$$

potenciálové koef.  $B_{ik} = B_{ki}$

$$W_k = \int_0^{Q_k} \varphi_{0k} \cdot dQ'_k = \int_0^{Q_k} (B_{ki} Q_i + B_{kk} Q'_k) dQ'_k \Rightarrow W_k = B_{ki} Q_i Q_k + \frac{1}{2} B_{kk} Q_k^2 \rightarrow W = W_i + W_k$$

příspěvek potenciálu na k-tém vodiči způsobený i-tým vodičem

Obrácený postup:  $W'_k = \frac{1}{2} B_{kk} Q_k^2$   
 $W' = W'_k + W'_i$   
 $W'_i = B_{ik} Q_k Q_i + \frac{1}{2} B_{ii} Q_i^2$   
 $W' = W$

## Thomsonova věta

- Náboje na soustavě pevných vodičů obklopených nevodivým prostředím jsou v rovnovážném stavu rozloženy po povrchu těchto vodičů vždy tak, aby energie výsledného elstat. pole byla minimální.

$$\frac{\partial W}{\partial \xi_i}$$

pro  $Q = \text{konst.}$  platí

$$\Delta W + \Delta A = 0$$

$$G_i = - \frac{\Delta W}{\Delta \xi_i}$$

$$\Delta W = \frac{1}{2} \sum_{i=1}^N Q_i \Delta \varphi_{0i}$$

$$\vec{F} = -\nabla W$$

$$G_i = \left( \frac{\partial W}{\partial \xi_i} \right)_{Q \text{ konst.}}$$

$$G_i = - \frac{\partial W}{\partial \xi_i}$$

$$dW \dots d\varphi_{0i}$$

pro  $\varphi_{0i} = \text{konst.}$

$$\Delta W + \Delta A = \Delta W_{\text{ext}}$$

$$\Delta A = \Delta W$$

$$dW_{\text{ext}} = \sum_{i=1}^N \varphi_{0i} dQ_i$$

$$G_i = \frac{\Delta W}{\Delta \xi_i}$$

$$dW = \frac{1}{2} \sum_{i=1}^N \varphi_{0i} dQ_i$$

$$G_i = \left( \frac{\partial W}{\partial \xi_i} \right)_{\varphi_{0i} \text{ konst.}}$$

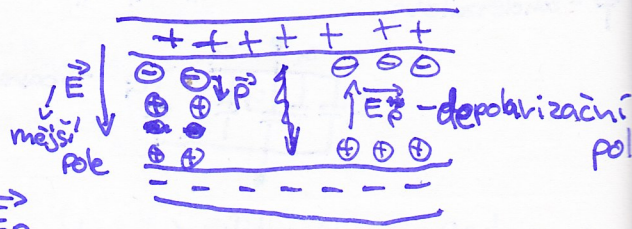
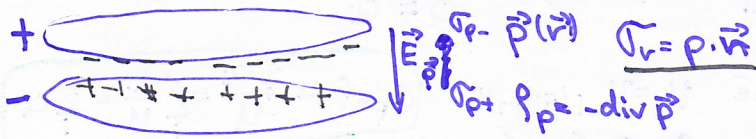


Kondenzátor  $\rightarrow Q = \text{konst}$   $\frac{1}{2} \frac{Q^2}{C}$  deskový  $\frac{\epsilon_0 \cdot S}{x} = C$

$F_x = -\frac{\partial}{\partial x} \left( \frac{1}{2} \frac{Q^2}{C} \right) = -\frac{1}{2} Q^2 \frac{\partial}{\partial x} \left( \frac{1}{C} \right) = -\frac{1}{2} Q^2 \frac{\partial}{\partial x} \left( \frac{x}{\epsilon_0 S} \right) = -\frac{1}{2} \frac{Q^2}{\epsilon_0 S} \cdot \frac{\epsilon_0 S}{x^2} = -\frac{1}{2} \frac{Q^2}{\epsilon_0 S} \cdot \frac{1}{x}$    
  $\rightarrow$  menší  $|x| \rightarrow$  větší  $|F|$    
 síla táhne desky k sobě

$U = \text{konst.}$

$F_x = \frac{\partial}{\partial x} \left( \frac{1}{2} C U^2 \right) = \frac{U^2}{2} \frac{\partial}{\partial x} (C) = \frac{U^2}{2} \left( -\frac{\epsilon_0 S}{x^2} \right) = -\frac{U^2 \cdot C}{2} \left( \frac{1}{x} \right)$    
 síla táhne desky k sobě



$\vec{E}, \vec{P}(\vec{r})$  vektor elektrické polarizace (hustota dip. momentu)

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int_V \left[ \frac{3(\vec{P} \cdot \vec{R}) \cdot \vec{R}}{R^5} - \frac{\vec{P}}{R^3} \right] dV$$

$\vec{P} = \chi_e \cdot \vec{E}_r \cdot \epsilon_0$    
 el. susceptibilita

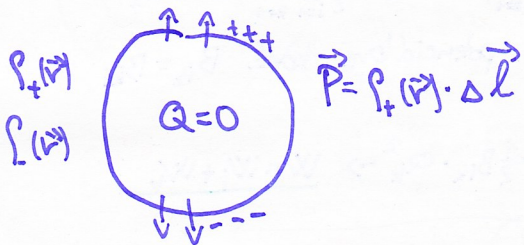
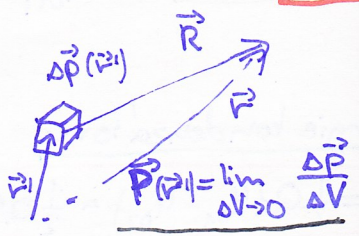
**IX.**

**Dielektrika** - nevodice (neobsahují volné náboje)

vektor polarizace  $\vec{P}(\vec{r})$  (hustota dipólového momentu)

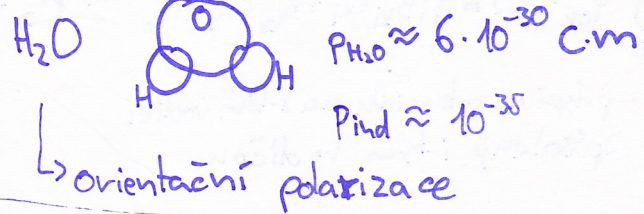
$\vec{E} \quad \vec{P}(\vec{r}) \approx f(\vec{E})$

$\rho_p = -\text{div} \vec{P}$    
  $\sigma_p = \vec{n} \cdot \vec{P}$



indukovaná polarizace

Dipólový moment v molekule.

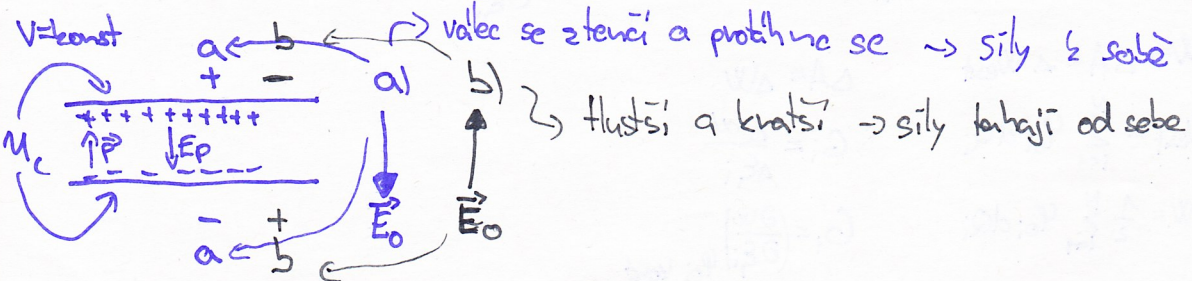
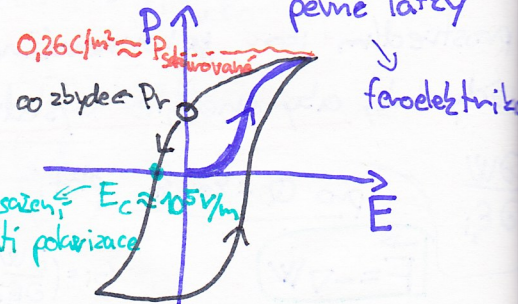


①  $\vec{P} = \epsilon_0 \chi_e \vec{E}$    
  $\rightarrow$  el. susceptibilita

$P \dots [\text{C}/\text{m}^2]$

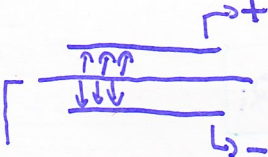
③  $\vec{P}$  nelineární fce  $\rightarrow$  většinou pevné látky

②  $\vec{P} = \underline{\epsilon} \vec{E}$  ( $\vec{P}$  může mít jiný směr než  $\vec{E}$ )  $\rightarrow$  tenzor   
  $P_x = \epsilon_{xx} E_x + \epsilon_{xy} E_y + \epsilon_{xz} E_z$





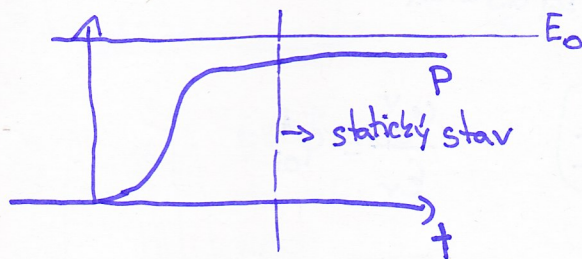
Dimebil:



např. zvukové měniče.  
dřív pláště.

Průběh ležící měřím

DÚ - Polarizační katastrofa



Rovnice elst. pole v dielektriku

$$\text{rot } \vec{E} = 0; \oint \vec{E} d\vec{l}$$

→ vázané náboje

$$\oint \vec{E} d\vec{s} = \frac{Q}{\epsilon_0}$$

Q + Q<sub>P</sub>

$$\epsilon_0 \oint \vec{E} d\vec{s} = \int_V \rho(r) dV + \int_V \rho_p(r) dV$$

volný náboj

Vektor el. indukce

$$\vec{D} \stackrel{\text{def}}{=} \epsilon_0 \vec{E} + \vec{P}$$

$$\oint \vec{D} d\vec{s} = Q$$

$$\text{div } \vec{D} = \rho$$

$$\oint \epsilon_0 \vec{E} d\vec{s} = Q - \int_V \text{div } \vec{P} dV = \oint \vec{P} d\vec{s}$$

$$\int_S (\epsilon_0 \vec{E} + \vec{P}) d\vec{s} = Q$$

$$\sigma_p^1 = \vec{n}_1 \cdot \vec{P}_1$$

$$\sigma_p^2 = \vec{n}_2 \cdot \vec{P}_2$$

$$\vec{n}_2 = -\vec{n}_1$$

$$\Phi = \Phi_1 + \Phi_2$$

$$\Phi = \Delta S \cdot (\sigma_p^1 + \sigma_p^2) \cdot \frac{1}{\epsilon_0}$$

$$\text{Pro } \sigma = 0 \rightarrow \vec{n}_1 (\vec{D}_2 - \vec{D}_1) = 0$$

$$\text{Pro } \sigma \neq 0 \rightarrow \vec{n}_1 (\vec{D}_2 - \vec{D}_1) = \sigma$$

Nespojitost na rozhraní dvou dielektrických materiálů.

$$\text{Div } \vec{E} = \frac{\sigma_{\text{tot}}}{\epsilon_0}$$

$$\text{Div } \vec{D} = \sigma$$

$$\vec{P} = \epsilon_0 \chi_e \vec{E} \quad (\text{předpoklad})$$

pro měkka dielektrika

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

$$\vec{D} = \epsilon_0 \vec{E} + \epsilon_0 \chi_e \vec{E}$$

$$\vec{D} = \epsilon_0 \vec{E} (1 + \chi_e)$$

$\epsilon_r$  - relativní permitivita

$$\vec{D} = \epsilon_0 \epsilon_r \vec{E}$$

permitivita prostředí

$$\begin{pmatrix} \epsilon_{xx} & \epsilon_{xy} & \epsilon_{xz} \\ \epsilon_{yx} & & \\ \epsilon_{zx} & & \end{pmatrix}$$

→ 6 nezávislých složek

$$\epsilon \sim \frac{1}{T - T_c}$$

→ s rostoucí teplotou narůstá chaos, který likviduje polarizaci

25 ... ethylalk  
5,9 ... NaCl  
13 ... Co<sub>2</sub>

....  $\epsilon_r$  ... H<sub>2</sub>O ... 81  
.... N<sub>2</sub>, O<sub>2</sub>, He ... 1,000...



## Pole soustavy nábojů v dielektriku

$Q_1, Q_2, \dots, Q_N$

$\varphi_{oi}^v$   $\varphi_{oi}^d$   $\rightarrow$  diel.  
 $\rightarrow$  ve vákuu



$$\oint_{S_i} \vec{E}_v d\vec{S} = \frac{Q_i}{\epsilon_0}$$

$$\oint \vec{D}_v d\vec{S} = Q_i$$

$$\oint \vec{D}_d d\vec{S} = Q_i$$

$$\vec{D}_v = \epsilon_0 \cdot \vec{E}_v$$

$$\vec{D}_d = \epsilon_0 \cdot \vec{E}_d$$

$$(\epsilon_0 \cdot \epsilon_r)$$

$$\epsilon_d = \frac{\epsilon_v}{\epsilon_r}$$

$$\epsilon_d = \frac{\epsilon_v}{\epsilon_r}$$

$$\frac{\varphi_{oi}^v}{\epsilon_r} = \varphi_{oi}^d$$

## Kapacita kondenzátoru - $C_d = C_v \cdot \epsilon_r$

$$\sigma_p = \vec{P} \cdot \vec{n} = P$$

$$\sigma_p \rightarrow E_0' \rightarrow P' \rightarrow \sigma_p'$$

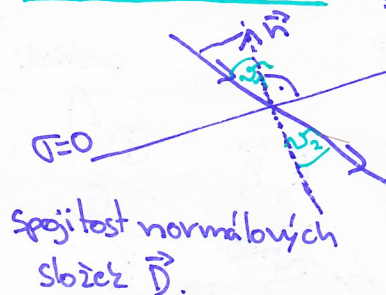


Piezoelektrický jev (feroelektrické d.) BaTiO<sub>3</sub>  
křemen (SiO<sub>2</sub>)

elektrostrikce

P. Currie

## Rozhraní dielektrik $\{\vec{E}_1, \vec{D}_1\}$



$$D_{2n} - D_{1n} = \sigma \quad (\text{Div } \vec{D} = \sigma)$$

$$D_1 \cos \alpha_1 = D_2 \cos \alpha_2$$

$$E_{1t} = E_{2t} \quad (\text{Rot } \vec{E} = 0)$$

$$E_1 \sin \alpha_1 = E_2 \sin \alpha_2$$

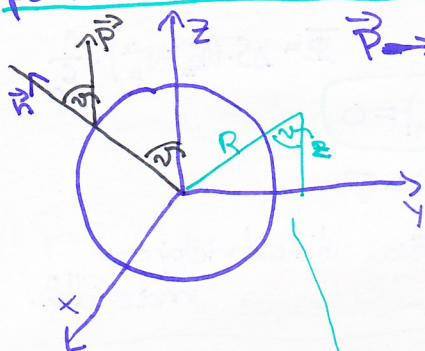
$$\frac{E_1}{D_1} \tan \alpha_1 = \frac{E_2}{D_2} \tan \alpha_2 \rightarrow \frac{\tan \alpha_1}{\tan \alpha_2} = \frac{\epsilon_1}{\epsilon_2}$$

$$\epsilon_1 \epsilon_1 = D_1$$

$$\epsilon_2 \epsilon_2 = D_2$$

Lom elektrických siločar na dielektrickém rozhraní

## El. pole v okolí homogenně polarizované diel. koule



$\vec{P} \rightarrow$  konst. vektor.  $= (0, 0, P)$

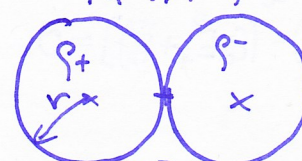
$$\sigma_p = \vec{P} \cdot \vec{n}$$

$$\sigma_p = \vec{P} \cdot \vec{n} = P \cdot \cos \alpha$$

$$\vec{E}(r) = ?$$

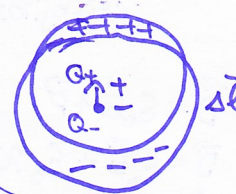
$$\varphi(r) = ?$$

$$|P_+| = |P_-| = P$$



$$Q_{\pm} = \frac{4}{3} \pi r^3 P$$

soustředné



$$\vec{P} = Q \cdot \vec{r}$$

$$Q = P \cdot V$$

$R > r$   
pole dipolu  $\vec{P}$

$$\vec{P} = \frac{4}{3} \pi r^3 \cdot \vec{P}$$

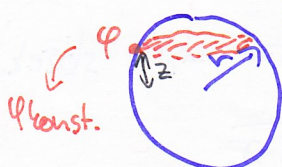
vektor polariza

$$\varphi(R) = \frac{1}{4\pi\epsilon_0} \frac{\vec{P} \cdot \vec{R}}{R^3}$$

$$\varphi(R) = \frac{1}{4\pi\epsilon_0} \frac{4}{3} \pi r^3 \frac{\vec{P} \cdot \vec{z}}{R^3}$$

$$\cos \alpha = \frac{z}{R}$$

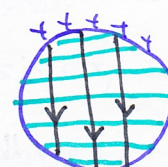
$$\text{pro } R=r \Rightarrow \varphi(r) = \frac{1}{3\epsilon_0} \cdot P \cdot z$$



$$\varphi(z) = \frac{1}{3\epsilon_0} P \cdot z$$

uvnitř koule  $\text{div } \vec{P} = \rho_p = 0$

$\varphi$  nemá extrém uvnitř koule



$$E_z = -\nabla \varphi = -\frac{P}{3\epsilon_0}$$

$$\vec{E}_p = -\frac{\vec{P}}{3\epsilon_0}$$

elektrické pole



## Homogenně zpolarizují

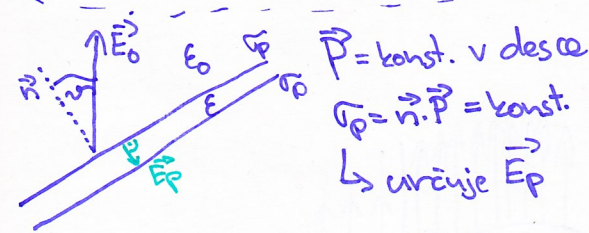
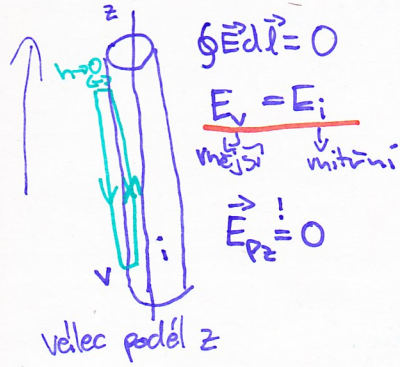
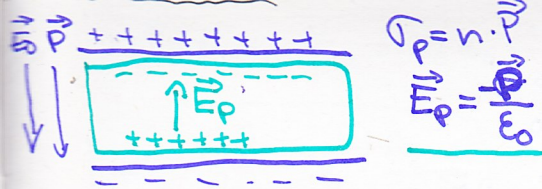
$$\vec{E}_p = (E_{px}, E_{py}, E_{pz}) \quad E_{px} = -N_x \cdot \frac{P_x}{\epsilon_0}$$

depolarizační faktor

	koule	deska	vallec
$N_x$	$\frac{1}{3}$	0	$\frac{1}{2}$
$N_y$	$\frac{1}{3}$	0	$\frac{1}{2}$
$N_z$	$\frac{1}{3}$	1	0

celkem musí být 1.

vallec podél osy x nebo y



$$\vec{E}_{\text{vlede}} = \vec{E}_0 + \vec{E}_p$$

$\vec{D}_1 \vec{E}$  musí splňovat hraniční podmínku

## Energie elstat. pole v dielektriku

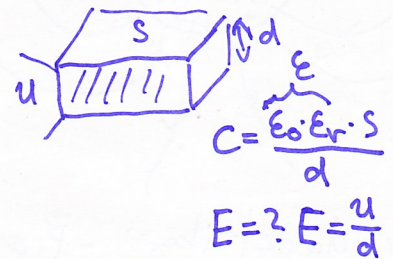
kondenzátor s diel. (rovinij)

$$W = \frac{1}{2} QU = \frac{1}{2} CU^2$$

$$= \frac{1}{2} \frac{\epsilon_0 \epsilon_r}{d} \cdot E^2 \cdot d \cdot S$$

$$W = \frac{1}{2} \vec{E} \cdot \vec{E} \cdot V$$

$$W = \frac{1}{2} \vec{D} \cdot \vec{E} \cdot V$$



→ lepší odvození než v knize  
→ tam je zbytečně složité  
 $w_e \rightarrow$  hustota energie elektrostatického pole

## Energie diel. tělesa v elst. poli

$$\Delta W = - \Delta V \cdot \vec{P} \cdot \vec{E}_0$$

"tvrdé" dielektrikum  $\vec{P}_0 = \text{konst}$

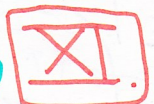
$$W_T = - \int_V \vec{P}_0 \cdot \vec{E}_0 \cdot dV$$

$$\Delta \vec{P} = \rho \Delta \vec{r} \quad \Delta W = \rho \Delta \vec{r} \cdot \vec{E} \quad \vec{P} = \chi \cdot \vec{E} \quad W_E = \chi \int_0^{E_0} \vec{E} \cdot d\vec{E} = \frac{1}{2} \chi E_0^2$$

$$W = W_T + W_E = - \int_V \vec{P}_0 \cdot \vec{E}_0 \cdot dV + \frac{1}{2} \int_V \vec{P}_0 \cdot \vec{E}_0 \cdot dV$$

$$W = - \frac{1}{2} \int_V \vec{P}_0 \cdot \vec{E}_0 \cdot dV$$

Dielektrická koule v homogenním elektrickém poli

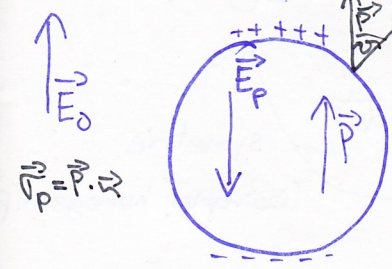


$$\vec{E}_p = - \frac{\vec{P}}{3\epsilon_0} \quad ; \quad \vec{E}_0 - \text{mější pole} \quad ; \quad \vec{E}_v = \vec{E}_0 + \vec{E}_p$$

$$\vec{P} = \epsilon_0 \chi_e \cdot \vec{E}_v = \epsilon_0 (\epsilon_r - 1) \cdot \vec{E}_v$$

$$\vec{E}_v = \vec{E}_0 - \frac{\vec{P}}{3\epsilon_0} \quad \vec{E}_v = \vec{E}_0 - \frac{1}{3\epsilon_0} \epsilon_0 (\epsilon_r - 1) \vec{E}_v$$

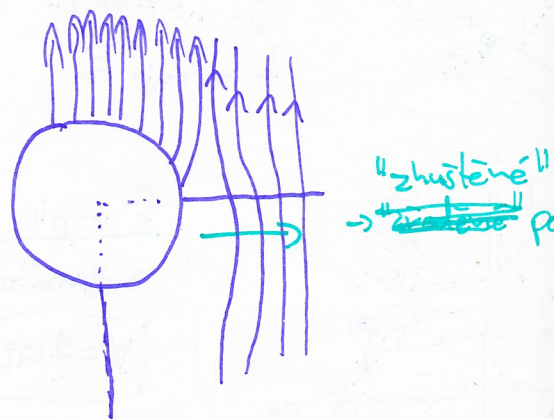
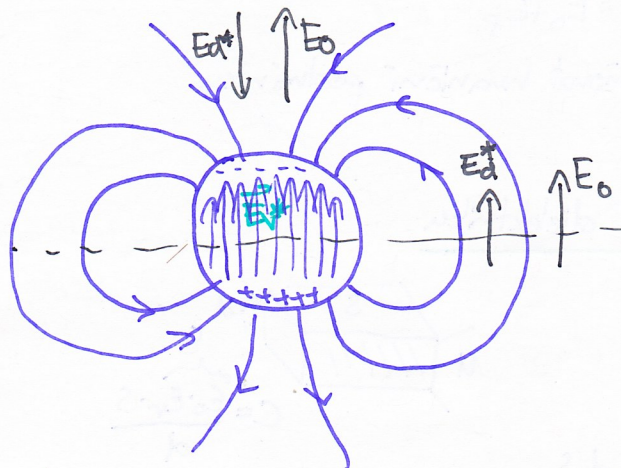
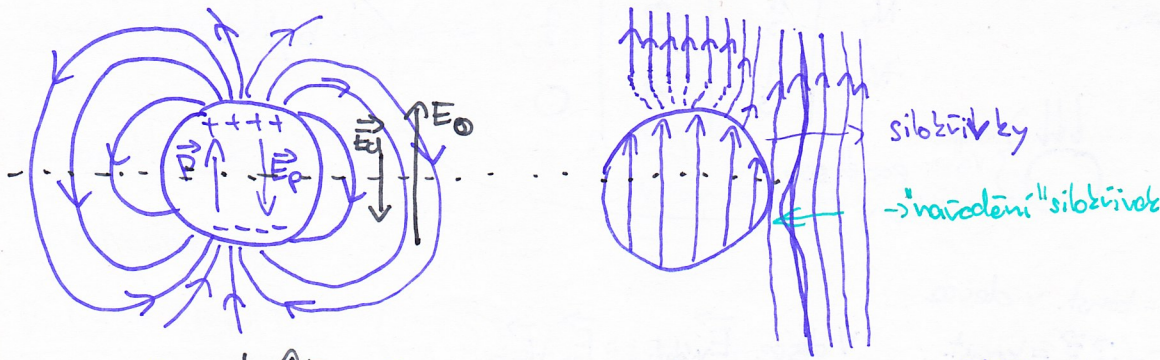
$$\vec{E}_v (1 + \frac{\epsilon_r - 1}{3}) = \vec{E}_0 \quad \vec{E}_v = \frac{3}{2 + \epsilon_r} \vec{E}_0$$





# Kulová dutina v homog. zpolarizovaném dielektriku

$\vec{E}_V^*$  - pole v dutině  
 $\vec{E}_V^* = \vec{E}_0 + \vec{E}_p^*$        $\vec{P} = \epsilon_0(\epsilon_r - 1) \cdot \vec{E}_0$   
 $\vec{E}_V^* = \vec{E}_0 + \frac{1}{3\epsilon_0} \cdot \vec{P}$        $\vec{E}_V^* = \vec{E}_0 + \frac{1}{3\epsilon_0} \epsilon_0(\epsilon_r - 1) \vec{E}_0$   
 $\vec{E}_V^* = \vec{E}_0 \left(1 + \frac{\epsilon_r - 1}{3}\right)$        $\boxed{\vec{E}_V^* = \frac{2 + \epsilon_r}{3} \vec{E}_0}$



Stav dielektrika -  $\vec{P}(\vec{r})$ ,  $\chi_e$ ,  $\epsilon_r$ ,  $\epsilon$   
makroskopicky      získáme experimentálně

$C = \frac{\epsilon_0 S}{d}$       statický případ  
 $C_d = \frac{\epsilon_0 \epsilon_r S}{d}$

mikroskopický pohled:  $\vec{P} = \vec{E}_{\text{lokální}} \cdot \alpha$        $\vec{P} = \vec{f}(\vec{E})$        $\vec{P} = \sum_i \alpha_i n_i \cdot \vec{E}_{\text{lok}}$   
 $\alpha_0 = ? \cdot \epsilon_r$       (koef. polarizace) - činitel polarizov  
 $\rightarrow$  koncentrace v jednotkovém objem

$\vec{P} = \alpha_0 n_0 \cdot \vec{E}_{\text{lok}}$        $\chi_e = \frac{\alpha_0 \cdot n_0}{\epsilon_0}$   
 $\epsilon_0 \chi_e \vec{E}$

$\vec{E}_0$  - v dielek. prostředí  
 $\alpha_0 = ?$   
 $\vec{E}_{\text{lok}} = \vec{E}_0 + \vec{E}_1 + \vec{E}_2$   
 $\vec{E}_0 + \vec{E}_1 = \frac{\epsilon_r + 2}{3} \vec{E}_0 \rightarrow$  pole v dutině  
 $\vec{E}_2 = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N \frac{3z_i \cdot z_i - r_i^2}{r_i^5}$   
 $\vec{P} = (0, 0, P)$   
 $\vec{P} \cdot \vec{r}_i = P \cdot z_i \rightarrow r_i^2 = x_i^2 + y_i^2 + z_i^2$   
 $\frac{3(\vec{P} \cdot \vec{r}) \cdot \vec{r}}{r^5} = \frac{\vec{P}}{r^3}$

$E_2 = \frac{P}{4\pi\epsilon_0} \sum \frac{2z_i^2 - x_i^2 - y_i^2}{r_i^5} = 0$   
 $\sum \frac{z_i^2}{r_i^5} = \sum \frac{y_i^2}{r_i^5} = \sum \frac{x_i^2}{r_i^5}$

Pokračení na další straně

symetrie (izotropní, homog.)



$$\vec{P} = \epsilon_0 (\epsilon_r - 1) \vec{E}_0$$

$$\vec{P} = n_0 q_0 \cdot \vec{E}_{lok} = n_0 q_0 \frac{2 + \epsilon_r}{3} \vec{E}_0$$

$$\epsilon_0 (\epsilon_r - 1) = n_0 q_0 \frac{2 + \epsilon_r}{3}$$

$$3 \epsilon_0 = n_0 q_0 \frac{\epsilon_r + 2}{\epsilon_r - 1}$$

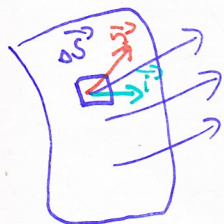
$$n_0 q_0 = 3 \epsilon_0 \frac{\epsilon_r - 1}{\epsilon_r + 2}$$

$A_m$  - hmotnost 1 molu  
 $N_A$  - Avogadrova konst.  
 $\rho$  - měrná hustota  
 $n_0 = \frac{\rho}{A_m} N_A$

$$\alpha_0 = \frac{3 A_m}{\rho \cdot N_A} \cdot \epsilon_0 \cdot \frac{\epsilon_r - 1}{\epsilon_r + 2}$$

↳ Clausius, Mossotti

## Elektrický proud



$$\Delta t \dots \Delta Q$$

$$I = \frac{\Delta Q}{\Delta t}$$

$$I(t) = \frac{dQ}{dt} \quad \text{okamžitý proud}$$

$$I(t) = \lim_{\Delta t \rightarrow 0} \frac{\Delta Q}{\Delta t} \quad \left[ \frac{C}{s} \right] [A]$$

hustota proudu:  $\vec{j}, \vec{i} \quad [\vec{j}] = A/m^2$

$$|\vec{i}| = \frac{\Delta I}{\Delta S}$$

objemová hustota proudu

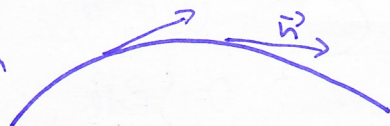


plošný proud

$$\sigma = \text{konst.}$$

$\frac{\Delta I}{\Delta l}$  hustota plošného proudu  $A/m$   
 $\vec{j}_s$

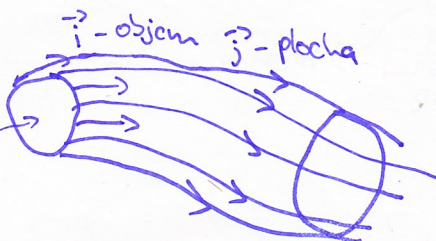
Proudová čára



$$\Delta I = \vec{\Delta l} \cdot \vec{j}$$

Proudová trubice

"to uvnitř"



Stacionární el. proud a el. pole

$$I = \frac{dQ}{dt}$$

$$I = \int_S \vec{i} \cdot d\vec{S}$$

$$\Delta Q = \Delta V \cdot \rho$$

$$\Delta V = \Delta \vec{S} \cdot \vec{v} \cdot \Delta t$$

$$I = \frac{\Delta Q}{\Delta t} = \Delta \vec{S} \cdot \vec{v} \cdot \rho$$

$$\vec{i} = \vec{v} \cdot \rho$$

$$\vec{i}_+ = \vec{v}_+ \cdot \rho_+$$

$$\vec{i}_- = \vec{v}_- \cdot \rho_-$$

$$\vec{i} = \vec{i}_+ + \vec{i}_-$$

$$|\rho_+| = |\rho_-|$$

$$\vec{i}_v = \vec{i}_+ - \vec{i}_-$$

$$\vec{v} = \vec{v}_+ - \vec{v}_-$$

↳ v důsledku  $\rho_+ = -\rho_-$

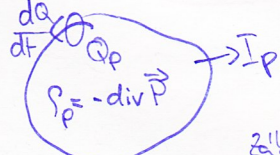
V látkách

a) kondukční proud

b) konvekční proud (volný prostor)

c) posuvný proud v dielektriku

$$I_p = -\frac{dQ_p}{dt}$$



$$Q_p = \int_V -\text{div} \vec{P} dV$$

$$\oint_S \vec{P} \cdot d\vec{S}$$

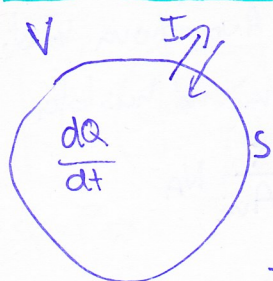
$$I_p = \frac{d}{dt} \oint_S \vec{P} \cdot d\vec{S}$$

zákon zachování náboje:  $I_p + \frac{dQ_p}{dt} = 0$

$$I_p = \oint \frac{\partial \vec{P}}{\partial t} \cdot d\vec{S} \rightarrow \vec{i}_p = \frac{\partial \vec{P}}{\partial t}$$



Zákon zachování náboje → v el. uzavřené soustavě se zachovává množství náboje



$$\frac{dQ}{dt} + I = 0 \rightarrow \frac{d}{dt} \int_V \rho dV + \oint_S \vec{j} \cdot d\vec{S} = 0$$

$$\frac{dQ}{dt} = \frac{d}{dt} \int_V \rho dV$$

$$\int_V \frac{\partial \rho}{\partial t} dV + \int_V \text{div} \vec{j} dV = 0$$

$$\int_V \left( \frac{\partial \rho}{\partial t} + \text{div} \vec{j} \right) dV = 0$$

$$\text{div} \vec{j} + \frac{\partial \rho}{\partial t} = 0$$

Rovnice kontinuity

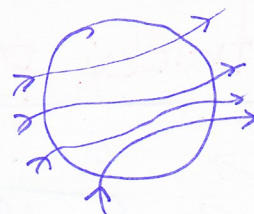
$$I = \oint_S \vec{j} \cdot d\vec{S}$$

stacionární  $\Leftrightarrow \frac{\partial \rho}{\partial t} = 0$

$$\Rightarrow \text{div} \vec{j} = 0$$

$$\oint_S \vec{j} \cdot d\vec{S} = 0$$

→ proudění jsou uzavřené křivky



$$\text{rot} \vec{E} = 0$$

$$\text{div} \vec{j} = 0$$

$$\oint \vec{D} \cdot d\vec{S} = Q$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

unita vodičů  $\vec{E} \neq 0$

$\vec{P}$ ?

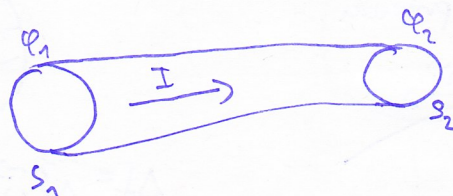
$$\text{Ohm: } I = \frac{U}{R}$$

$$P = I \cdot U$$

Ohmův zákon : G.S. Ohm

$$I = \frac{U}{R} \rightarrow \text{el. odpor}$$

1 Ω ... 14



$$U = \varphi_1 - \varphi_2$$

$$U = \int_1^2 \vec{E} \cdot d\vec{l}$$

$$R = \rho_R \cdot \frac{l}{S}$$

→ měrný odpor

$$\rho_R \dots [\Omega \cdot m]$$

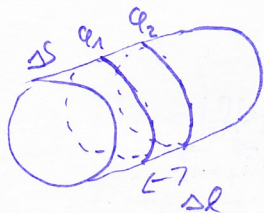
$$\gamma = \frac{1}{\rho_R}$$

→ měrná vodivost

Vodivost :  $G = R^{-1} = \frac{1}{\Omega} \dots S$  (Siemens)

$$\gamma = \frac{1}{\rho_R} (\Omega m)^{-1}$$

Diferenciální forma O.Z.



$$\Delta U = \varphi_1 - \varphi_2 = \vec{E} \cdot \Delta \vec{l}$$

$$R = \frac{1}{\gamma} \frac{\Delta l}{\Delta S}$$

$$I = \vec{j} \cdot \Delta \vec{S}$$

$$I = \frac{\Delta U}{R} = \gamma \frac{\vec{E} \cdot \Delta \vec{l}}{\Delta l} \cdot \Delta S = \vec{j} \cdot \Delta \vec{S} \rightarrow \boxed{\gamma \cdot \vec{E} = \vec{j}} \text{ ("bodově")}$$

$$j_i = \sigma_{ij} \cdot E_j$$

→ tenzor vodivosti

$$\mu \rightarrow \text{pohyblivost} \quad \vec{v} = \mu \cdot \vec{E}$$

$$\rho = \text{div} \vec{D} = \text{div} \epsilon \cdot \vec{E} = \text{div} \frac{\epsilon}{\gamma} \cdot \vec{j}$$

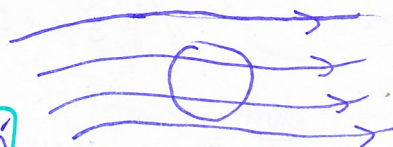
$$\int_V \frac{\epsilon}{\gamma} \text{div} \vec{j} = 0$$

$$\underline{\rho = -\text{div} \vec{P} = -\text{div} (\epsilon_0 \chi_e \cdot \vec{E}) = 0}$$



$$\begin{aligned}\operatorname{div} \vec{i} &= 0 & \rho &= 0 & \rho_p &= 0 \\ \operatorname{div} \vec{j} &= 0 & \rightarrow \operatorname{div} \vec{E} &= 0 \\ \operatorname{div} \vec{p} &= 0\end{aligned}$$

$$\oint \vec{D} d\vec{S} = 0$$



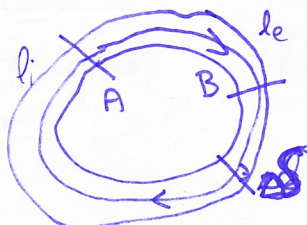
## Ohmův zákon pro nehomogenní vodiče

$\oint \vec{E} d\vec{l} = 0 \rightarrow$  statické el. pole je konzervativní

$$\vec{i} = \gamma \cdot \vec{E}$$

$$\int_A^B \frac{\vec{i}}{\gamma} d\vec{l} = \int_A^B \vec{E} d\vec{l}$$

vtišťená elektromotorická síla



$$I \int_A^B \frac{d\vec{l}}{\Delta S \cdot \gamma} = \int (\vec{E} + \vec{E}^*) d\vec{l}$$

elektromotorické napětí

$$I \cdot R_{AB} = U_{AB} + \mathcal{E}_{AB}$$

$$I \cdot R = \mathcal{E} \quad I = \frac{\mathcal{E}}{R}$$

$$\vec{E}^* = q \cdot \vec{E} - \text{vtišťená intenzita}$$

$$\vec{i} = \gamma (\vec{E} + \vec{E}^*)$$

$$R_i = \int_{R_i} \frac{d\vec{l}}{\gamma \Delta S} \quad |\vec{E}_i| |\vec{E}_e| \rightarrow \int_{R_i} \vec{E}_i d\vec{l} + \int_{R_e} \vec{E}_e d\vec{l} = 0$$

$$R_e \quad \int \vec{E}^* d\vec{l} = \mathcal{E} \quad R_i I = \int_{R_i} \vec{E}_i d\vec{l} + \mathcal{E}$$

$$-\int_{R_i} \vec{E}_i d\vec{l} = \mathcal{E} - R_i I \quad U_0 = \mathcal{E} - R_i I$$

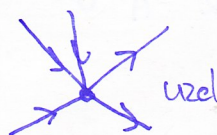
svorkové napětí

$$R_i \cdot I + R_e \cdot I + R_j \cdot I + R_v \cdot I = \mathcal{E}$$

$$I U_0 = \mathcal{E} I - R_i I^2$$

## Kirchoffova pravidla

1.)



uzel

$$\sum_{i=1}^N I_i = 0$$

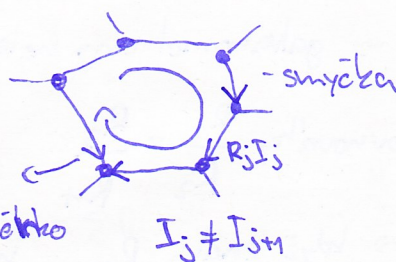
$$\operatorname{div} \vec{i} = 0$$

$$\oint \vec{i} d\vec{S} = 0$$

uzel (•)

větev (•—•)

proti smyčce ← opačně znaménko

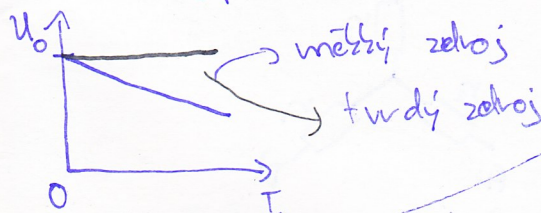


$$I_j \neq I_{jm}$$

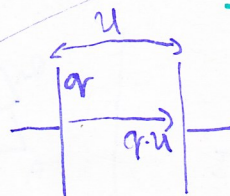
2) součet elmot. napětí  $\sum_{i=1}^N \mathcal{E}_i$

se musí rovnat součtu úbytků napětí na jednotlivých větvích smyčky  $\sum_{j=1}^K R_j I_j$

## Zatěžovací přírůstek



Ohmův z., Jouleův z.



$$q(\ell_1 - \ell_2)$$

$$U_k = q \cdot U$$

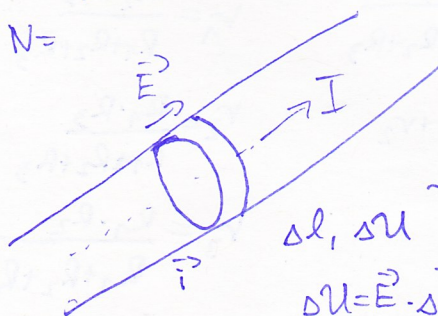
$$\Delta U = \Delta Q \cdot U \quad \text{za čas } \Delta t$$

$$N = \frac{\Delta Q}{\Delta t} \cdot U = I \cdot U$$

$$\Delta Q = I \cdot \Delta t$$

$$N = U \cdot I \rightarrow \text{Jouleovo teplo}$$

N =



$$\Delta \ell, \Delta U$$

$$\Delta U = \vec{E} \cdot \Delta \vec{\ell}$$

$$\Delta I = \Delta S \cdot \vec{i}$$

$$\Delta N = \Delta U \cdot \Delta I = (\vec{E} \cdot \Delta \vec{\ell}) (\Delta \vec{S} \cdot \vec{i})$$

$$\Delta N = (\vec{i} \cdot \vec{E}) (\Delta \vec{\ell} \cdot \Delta \vec{S})$$

$$n = \frac{\Delta N}{\Delta V} = \vec{i} \cdot \vec{E}$$

hustota výkonu  $i = \gamma \cdot \vec{E}$

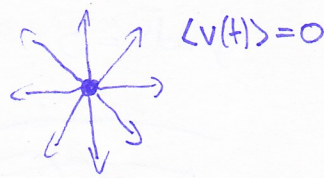
$$n = \gamma E^2$$



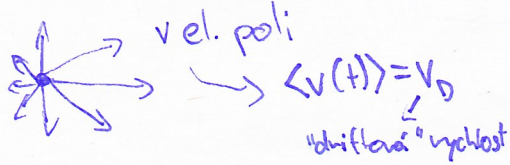
## Drudeho model

$$m \left( \frac{dv(t)}{dt} + \frac{v(t)}{\tau} \right) = qE$$

$\rightarrow$  konst.



$$\langle v(t) \rangle = 0$$



vel. poli

$$\langle v(t) \rangle = v_D$$

"driftová" rychlost

$$\frac{dv(t)}{dt} = 0 \dots \text{v ustáleném stavu}$$

$$\frac{mv_D}{\tau} = qE$$

$$\vec{j} = \rho \vec{v}$$

$$v_D = \frac{\tau \cdot q}{m} \cdot E \rightarrow \vec{v}_D = \mu \cdot \vec{E}$$

$\mu \rightarrow$  pohyblivost náboje

$$\rho = n_0 \cdot q$$

$\rightarrow$  koncentrace nosičů náboje

$$\vec{j} = \rho \vec{v} \rightarrow \vec{j} = n_0 \cdot q \cdot \frac{\tau \cdot q}{m} \cdot \vec{E}$$

$$\underline{\underline{\eta = \frac{n_0 \cdot q^2 \cdot \tau}{m}}}$$

$$m \left( \frac{dv}{dt} + \frac{v}{\tau} \right) = 0 \rightarrow \text{"upnuté" pole}$$

$$\frac{dv}{v} = -\frac{dt}{\tau} \quad \int_0^+ \rightarrow \ln v(t) \Big|_0^+ = -\frac{t}{\tau}$$

$$\frac{v(t)}{v(0)} = e^{-\frac{t}{\tau}}$$

$$v(t) = v_0 \cdot e^{-\frac{t}{\tau}}$$

$\tau \rightarrow$  čas kon.

## Měření odporu

$$R = \frac{U}{I}$$

rezistor, odpor [ $\Omega$ ]

- voltmetr

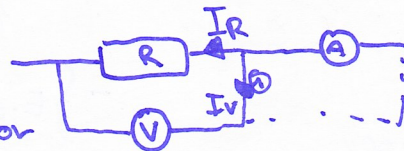


$\rightarrow$  ideálně  $\infty$  odpor

- ampérmetr



$\rightarrow$  ideálně 0 odpor



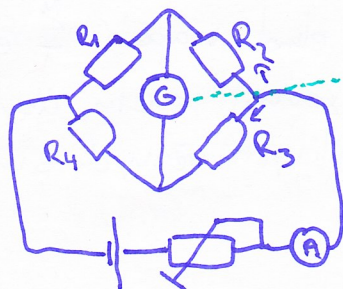
$$U_R + U_A = U$$

$$R_V \gg R$$

$$I = I_R + I_V$$

## Můstkové zapojení

Wheatson



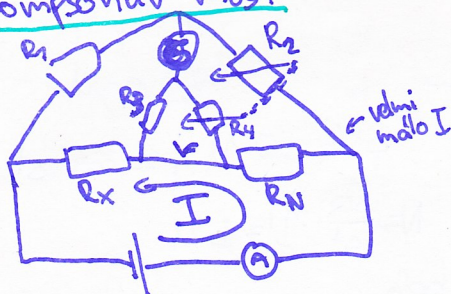
$\odot \rightarrow$  galvanometr

splněna  $\rightarrow$  galvanometrem neteče proud

$$\text{Podmínka rovnováhy} \quad \frac{R_1}{R_2} = \frac{R_3}{R_4}$$

$R_3 = R_x \rightarrow$  když známe  $R_{1,2,4}$ , můžeme  $R_x$  do

## Thompsonův most

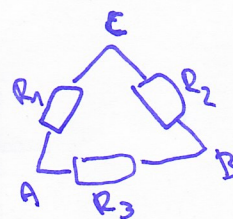


Podmínka rovnováhy

$$R_2 = R_4$$

$$R_1 = R_3 = 1000 \Omega$$

$$\rightarrow R_x = R_N \frac{R_3}{R_4}$$



$$R_{AB} = R_{A'B'}$$

$$R_{BC} = R_{B'C'}$$

$$R_{AC} = R_{A'C'}$$

$$R_{AB} = \frac{(R_1 + R_2) \cdot R_3}{R_1 + R_2 + R_3}$$

$$R_{A'B'} = r_1 + r_2$$

$$r_1 = \frac{R_2 \cdot R_3}{R_1 + R_2 + R_3}$$

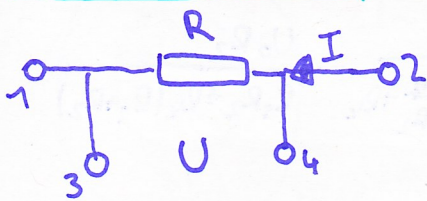
$$r_2 = \frac{R_1 \cdot R_3}{R_1 + R_2 + R_3}$$

$$r_3 = \frac{R_1 \cdot R_2}{R_1 + R_2 + R_3}$$

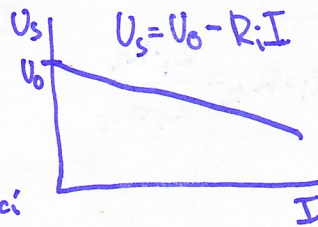
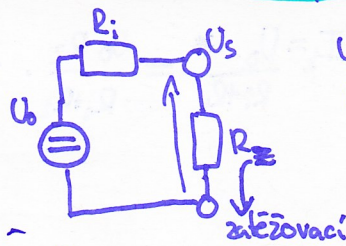
$\rightarrow$  zjišťování odporů drátů (vodičů)



## 4 bodová metoda



## Výkonové přizpůsobení

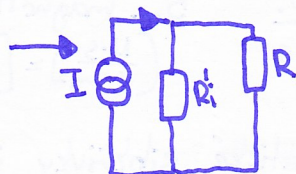
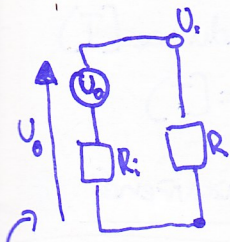


$$N = U_s \cdot I$$

$$I = \frac{U_0}{R_i + R_z}$$

$$\frac{dN}{dR_z} = 0$$

## Napěťový ↔ proudový zdroj



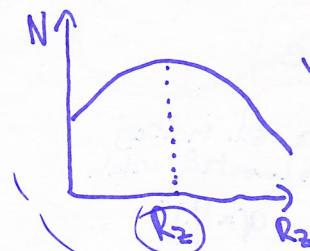
A:  $I_R = \frac{U}{R_i + R}$ ;  $U_0 = I_R \cdot R_i + I_R \cdot R$

B:  $I = I_R + I_{R_i}$

$$I_{R_i} = I_{R_i} \cdot R_i \Rightarrow I_{R_i} = \frac{I_R \cdot R}{R_i}$$

$$I = I_R \left(1 + \frac{R}{R_i}\right)$$

$$I = \frac{U_0}{R_i + R} \cdot \frac{R_i + R}{R_i}$$



vyjde  $R_z = R_i$

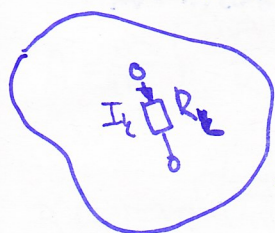
↳ výpočet za DÚ

## Nortonova věta

$$R_i = R_i'$$

$$I = \frac{U_0}{R_i}$$

## Věta o superpozici



$E_i, R_i \quad i=1, \dots, N$

Při zapnutí i-tého zdroje a ostatních... ( $E_L$ )  
vypnutých ( $L \neq i$ )

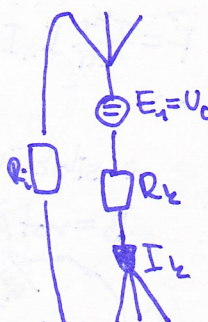
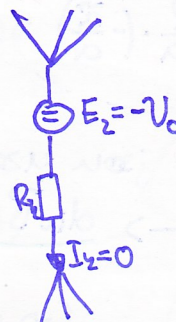
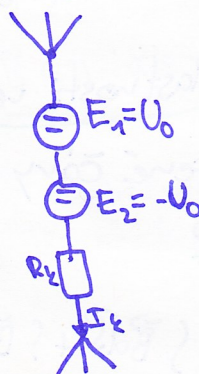
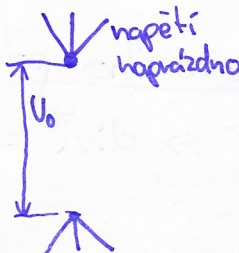
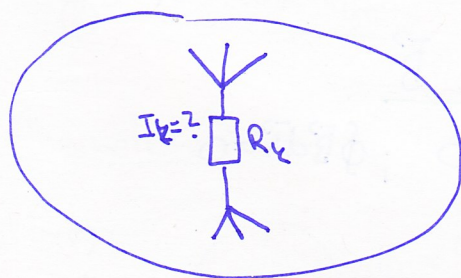
$$I_L^{(i)} \dots$$

$$I_L = \sum_{i=1}^N I_L^{(i)}$$

## II. Kirchhoff pravidlo

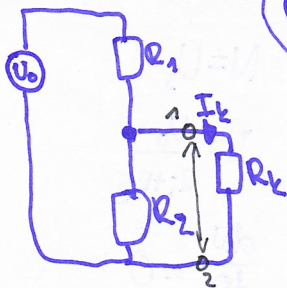
$$\sum_{i=1}^N E_i = \sum_{j=1}^q R_j I_j \Leftrightarrow E_i = \sum_{j=1}^q R_j I_j^{(i)} \Rightarrow \sum_{i=1}^N \sum_{j=1}^q R_j I_j^{(i)} = \sum_{j=1}^q R_j \sum_{i=1}^N I_j^{(i)}$$

## Théveninova věta



$$I_L = \frac{U_0}{R_i + R_L}$$





$$U_0 \frac{R_2}{R_1 + R_2} \rightarrow \text{napětí naprázdno}$$

$$R_i = R_{12} = \frac{R_1 \cdot R_2}{R_1 + R_2}$$

$$I_k = \frac{U_0}{R_1 + R_k} = \frac{U_0 R_2}{R_1 + R_2} \cdot \frac{1}{\frac{R_1 R_2}{R_1 + R_2} + R_k} = \frac{U_0 R_2}{R_1 R_2 + R_k (R_1 + R_2)}$$

## Magnetické pole

• Sílové působení na el. náboj

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \rightarrow \text{Lorentzův vztah}$$

$$q = \rho \cdot V$$

magnetické p.  
vektor indukce

$$\vec{B} \dots \text{magnetická indukce}$$

$$\left[ \frac{N \cdot s}{C \cdot m} \right] = \left[ \frac{N}{A \cdot m} \right] = [T]$$

$$\vec{F}_m = V \cdot \rho \cdot \vec{v} \times \vec{B}$$

$$\vec{f} = \vec{j} \times \vec{B} \rightarrow \text{objemová hustota magnetické síly}$$

vektor proudové hustoty

$$C = \frac{\mu_0}{2\pi}$$

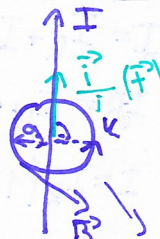
$$B = C \cdot \frac{I}{a}$$

$$\text{div } \vec{j} = 0$$

$$c = 2 \cdot 10^{-7}$$

permeabilita vakua

magnetické sílové čáry jsou uzavřené



pravidlo pravé ruky

$$\oint \vec{B} d\vec{l} = \frac{\mu_0}{2\pi a} I = \mu_0 I$$

$$k = \frac{1}{4\pi\epsilon_0} = \frac{c^2}{10^7} \dots \rightarrow \text{tedy jako rychlost světla}$$

XV

$$[\epsilon_0] \dots \frac{F}{m} \quad [\mu_0] \dots \frac{H}{m}$$

$$\vec{B} = \frac{\mu_0}{2\pi} I \frac{\vec{r} \times \vec{a}}{a^2}$$

$$\vec{B} = \frac{\mu_0}{2\pi} I \frac{\vec{r} \times \vec{a}}{a^2}$$

$$C^2 = \frac{1}{\epsilon_0 \mu_0}$$

$$F = C \cdot \frac{I_1 \cdot I_2}{a} \cdot l \quad [C] \quad \frac{N}{A^2}$$

$$\vec{B} = \frac{\mu_0}{2\pi} I_1 \frac{\vec{r} \times \vec{a}}{a^2}$$

$$\vec{F} = \vec{f} \cdot V^l \quad V^l = S \cdot l \quad S = \frac{I_2}{i_2}$$

$$\vec{F} = \vec{i}_2 \times \frac{\mu_0}{2\pi} I_1 \frac{(\vec{r} \times \vec{a})}{a^2} \cdot \frac{I_2}{i_2} \cdot l$$

$$B = \frac{1}{c^2} (\vec{u} \times \vec{E}^*)$$

$$\text{rot}(\text{grad}) \equiv 0$$

$$\vec{F} = \frac{\mu_0}{2\pi} I_1 I_2 \frac{\vec{r} \times (\vec{r} \times \vec{a})}{a^2} \cdot l$$

$$\vec{r} \times (\vec{r} \times \vec{a}) = \vec{r}(\vec{r} \cdot \vec{a}) - \vec{a}(\vec{r} \cdot \vec{r})$$

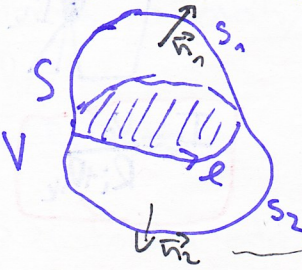
$$\vec{F} = \frac{\mu_0}{2\pi} I_1 I_2 \cdot \frac{l}{a} \cdot (-\frac{\vec{a}}{a})$$

Vlastnosti vektorového pole  $\vec{B}$

$\rightarrow$  sílové čáry jsou uzavřené čáry

$$\rightarrow \text{div } \vec{B} = 0 ; \oint \vec{B} d\vec{s} = 0$$

$$\vec{B} = \text{rot } \vec{A} \rightarrow \text{div } \vec{B} = 0$$

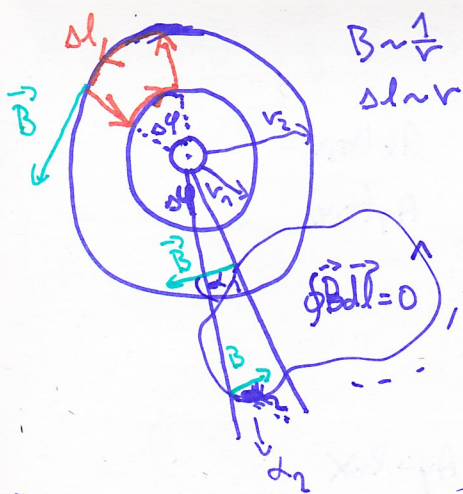


$$\oint \vec{B} d\vec{s} = \oint \vec{B} d\vec{s} + \oint \vec{B} d\vec{s} = \oint \text{rot } \vec{A} d\vec{s} + \oint \text{rot } \vec{A} d\vec{s} = \oint \vec{A} d\vec{l} - \oint \vec{A} d\vec{l} = 0$$

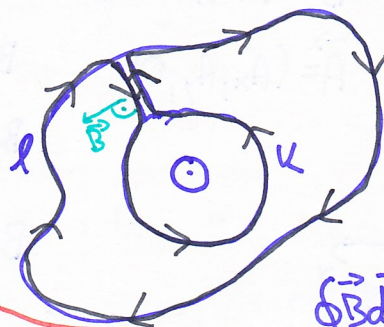
"nezvlnové"; solenoidální

$$\vec{B} \dots \vec{A}, \vec{A} + \nabla \phi$$





$$\frac{1}{\cos \alpha_2} \cdot \cos \alpha_2$$



$$\oint \vec{B} d\vec{l} = \mu_0 \cdot I$$

$$\oint \vec{B} d\vec{l} = 0$$

$$\oint \vec{B} d\vec{l} - \oint \vec{B} d\vec{l} = 0$$

$$\oint \vec{B} d\vec{l} = \mu_0 \cdot I$$

$$\vec{i}(\vec{r})$$

$$\vec{B}(\vec{r})$$



$$\text{div } \vec{i} = 0$$

$$\oint \vec{B} d\vec{l} = \mu_0 \int \vec{i} d\vec{S}$$

$$\int \text{rot } \vec{B} d\vec{S} = \mu_0 \int \vec{i} d\vec{S}$$

$$\int (\text{rot } \vec{B} - \mu_0 \vec{i}) d\vec{S} = 0$$

$$\text{rot } \vec{B} = \mu_0 \vec{i}$$

Vektorový potenciál magn. pole.

$$\vec{B} = \text{rot } \vec{A} \quad (+\nabla \varphi) \quad \text{rot } \vec{B} = \mu_0 \vec{i}$$

$$\text{rot rot } \vec{A} = \mu_0 \vec{i}$$

$$\nabla \times (\nabla \times \vec{A}) = -\Delta \vec{A} + \nabla(\nabla \cdot \vec{A})$$

$$\Delta \vec{A} = -\mu_0 \vec{i}$$

$$(\Delta \varphi = -\frac{\rho}{\epsilon_0})$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{R} \cdot dV$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{i}(\vec{r}')}{R} dV$$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}') \vec{R}}{R^3} dV$$

$$\vec{B}(\vec{r}) = \text{rot} \left( \frac{\mu_0}{4\pi} \int \frac{\vec{i}(\vec{r}')}{R} dV \right)$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \text{rot} \left( \frac{\vec{i}(\vec{r}')}{R} \right) dV$$

$$\text{rot } \vec{i}(\vec{r}') = 0$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{i} \times \vec{R}}{R^3} dV$$



Princip superpozice a  $\vec{A}(\vec{r})$

$$\text{div } \vec{B} = 0 + \text{A. z.} \rightarrow 3 \text{ Poissonova rovnice } \Delta \vec{A} = -\mu_0 \vec{i} \rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{i}(\vec{r}')}{R} dV \dots$$

$$\dots \rightarrow \vec{B} = \text{rot } \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{i}(\vec{r}') \times \vec{R}}{R^3} dV \leftarrow \text{B.-S. z.}$$

stacionární případ:  $\text{div } \vec{i} = 0$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} I \oint \frac{d\vec{l} \times \vec{R}}{R^3}$$

Magnetický tok

$$\vec{B}(\vec{r})$$

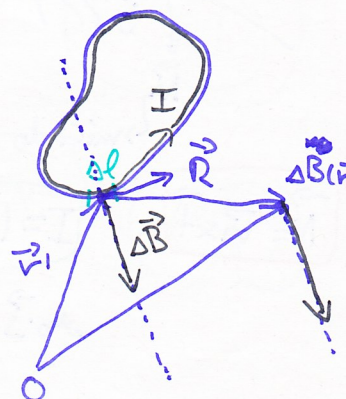


$$\Phi = \int_S \vec{B} d\vec{S} \quad (\text{Weber})$$

magnetický tok

$$\Phi = \int_S \text{rot } \vec{A} d\vec{S} = \oint_L \vec{A} d\vec{l}$$

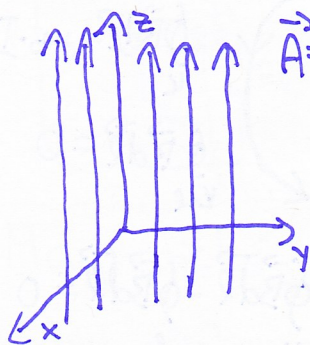
vektor magnetické indukce, všude spojitý





$$\vec{B} = (0, 0, B_0) \quad \vec{A} = ?$$

$$\text{rot } \vec{A} = \vec{B} \quad \vec{B} = \nabla \times \vec{A} \rightarrow \vec{B} \perp \vec{A}$$



$$\vec{A} = (A_x, A_y, 0)$$

$$B_x = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} = 0$$

$$A_x(x, y)$$

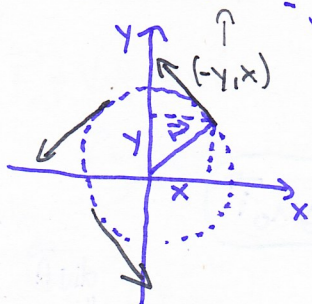
$$A_y(x, y)$$

$$B_y = \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} = 0$$

$$B_z = \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} = B_0$$

$$\vec{A} = \frac{1}{2} B_0 (-y, x)$$

$$\begin{cases} A_y = \frac{1}{2} B_0 x \\ A_x = -\frac{1}{2} B_0 y \end{cases} \quad \begin{cases} A_x = 0 \rightarrow \frac{\partial A_y}{\partial x} = B_0 \Rightarrow A_y = B_0 x \\ A_y = 0 \rightarrow -\frac{\partial A_x}{\partial y} = B_0 \Rightarrow A_x = -B_0 y \end{cases}$$



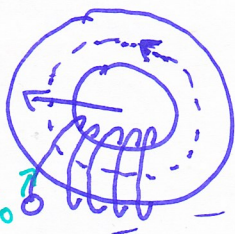
$$\vec{A} = -\frac{1}{2} \vec{r} \times \vec{B} \rightarrow \vec{A} = \frac{1}{2} \vec{B} \times \vec{r}$$

### Magnetické pole toroidní cívky

$$2\pi R N_0$$

závitů

počet závitů na jednotku délky



$$B = ?$$

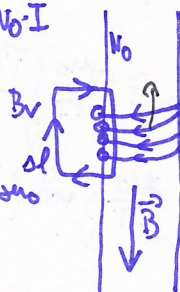
$$\oint \vec{B} d\vec{l} = \mu_0 \cdot I$$

$$B \cdot 2\pi R = \mu_0 \cdot 2\pi R N_0 \cdot I$$

$$B = \mu_0 \cdot N_0 \cdot I$$

### Nekonečně dlouhý solenoid

$$B = \mu_0 \cdot N_0 \cdot I$$



Takže dostáváme  $B_r = 0!$

vně solenoidu je nulová magnetická indukce

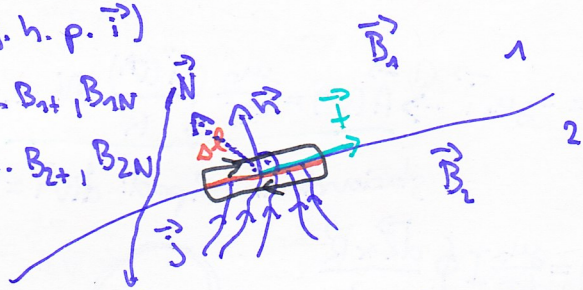
$$\Delta l \cdot B_{1N} + \Delta l \cdot B_{2N} = \Delta l \cdot N_0 \cdot I \cdot \mu_0$$

### Plošná hustota proudu $\vec{j}$

(obj. h. p.  $\vec{i}$ )

$$\vec{B}_1 \dots B_{1+}, B_{1N}$$

$$\vec{B}_2 \dots B_{2+}, B_{2N}$$



$$B_{1N} = B_{2N}$$

$$\text{div } \vec{B} = 0$$

$$\oint \vec{B} d\vec{S} = 0$$

$$B_{1N} \cdot \Delta S + B_{2N} \cdot \Delta S = 0$$

"analógie gausse"  $\rightarrow$  "co vteče, musí vytéct"

$$\vec{N} = \vec{n} \times \vec{t}$$

$$I = (\vec{j} \cdot \vec{N}) \Delta l = j_N \cdot \Delta l$$

$$\oint \vec{B} d\vec{l} = \mu_0 \cdot I$$

$$\mu_0 \cdot \vec{j} \cdot \vec{N} \cdot \Delta l = (\vec{B}_1 \cdot \vec{N} - \vec{B}_2 \cdot \vec{N}) \Delta l \rightarrow (B_{1N} - B_{2N}) \Delta l = \mu_0 \cdot \vec{j} \cdot \vec{N}$$

$$\vec{n} \times (\vec{E}_1 - \vec{E}_2) = 0 \quad \text{Rot } \vec{E} = 0$$



$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_S \frac{\vec{j} \times \vec{R}}{R^3} dS$$

$\vec{B} = \text{rot } \vec{A}$

$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int_S \frac{\vec{j} \times \vec{R}}{R^3} dS$

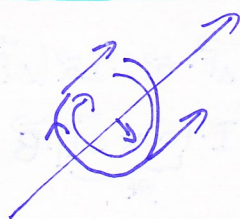
→ spojitě všude kromě bodů plochy  
→ na ploše není definováno

$$\vec{A}(\vec{r}) = \frac{1}{2} \vec{B} \times \vec{r} \quad \vec{B} = \nabla \times \vec{A}$$

$$\text{rot rot } \vec{A} = \mu_0 \vec{j}$$

$$\nabla \cdot \vec{A} = 0 \quad (\text{A je solenoidální})$$

**XVII.**

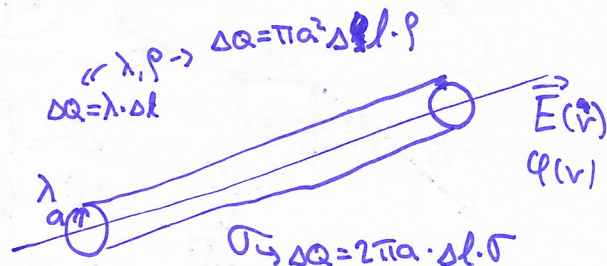


$$B = \frac{\mu_0}{2\pi} \frac{I}{r}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{j}}{r} dV$$

$$\varphi(r)? \quad \varphi = \frac{1}{4\pi\epsilon_0} \int \frac{\rho}{R} dV$$

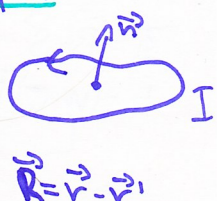
$$A_x(R)? \quad A_x = \frac{\mu_0}{4\pi} \int \frac{j_x}{R} dV$$



Magnetický dipól

$$\text{div } \vec{j} = 0$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} I \oint \frac{d\vec{l}}{r}$$



$$\oint \frac{d\vec{l}}{R} = \oint \frac{\vec{c} d\vec{l}}{R} = \int_S \text{rot} \left( \frac{\vec{c}}{R} \right) d\vec{S} = \int_S \left( \frac{\vec{R}}{R^3} \times \vec{c} \right) d\vec{S} = \vec{c} \left( \oint d\vec{S} \times \frac{\vec{R}}{R^3} \right)$$

$$\nabla \times \left( \frac{\vec{c}}{R} \right) = \nabla \times \left( \frac{\vec{c}}{R} \right) = \nabla \times \left( \frac{\vec{c}}{R} \right)$$

$$\nabla \times (s \cdot \vec{V}) = \nabla s \times \vec{V} + s (\nabla \times \vec{V})$$

$$s = \frac{1}{R} \quad \vec{V} = \vec{c}$$

$$\nabla \frac{1}{R} = -\frac{\vec{R}}{R^3}$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} I \oint \frac{d\vec{S} \times \vec{R}}{R^3}$$

V limitním případě  $\vec{S} \rightarrow 0$   
 $I \rightarrow \infty$

$$\left[ \varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{R}}{R^3} \right]$$

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0}{4\pi} \nabla \times \left( \vec{m} \times \frac{\vec{R}}{R^3} \right)$$

magnetický moment proudové smyčky  
 $\vec{m} \dots$

$$\text{rot} \left( \vec{m} \times \frac{\vec{R}}{R^3} \right)$$

BAC - CAB

$$\nabla \times (\vec{V}_1 \times \vec{V}_2) = \nabla \times (\vec{V}_1 \times \vec{V}_2) + \nabla \times (\vec{V}_2 \times \vec{V}_1) = \vec{V}_1 (\nabla \cdot \vec{V}_2) - \vec{V}_2 (\nabla \cdot \vec{V}_1) + (\vec{V}_2 \cdot \nabla) \vec{V}_1 - (\vec{V}_1 \cdot \nabla) \vec{V}_2$$

$\vec{m} = \vec{V}_1 \quad \frac{\vec{R}}{R^3} = \vec{V}_2$  po dosazení

$$\vec{B} = \frac{\mu_0}{4\pi} \left( -\vec{m} \nabla \right) \frac{\vec{R}}{R^3}$$

Dokažme, že platí  $\nabla (\vec{m} \cdot \frac{\vec{R}}{R^3}) = (\vec{m} \nabla) \frac{\vec{R}}{R^3}$

$$\nabla (\vec{V}_1 \cdot \vec{V}_2) = (\vec{V}_1 \nabla) \vec{V}_2 + (\vec{V}_2 \nabla) \vec{V}_1 + \vec{V}_1 \times \text{rot } \vec{V}_2 + \vec{V}_2 \times \text{rot } \vec{V}_1$$

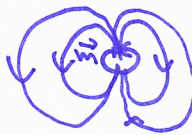
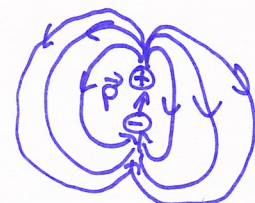
$\vec{V}_1 = \vec{m}$   
 $\vec{V}_2 = \frac{\vec{R}}{R^3}$

$$\Rightarrow \nabla (\vec{m} \cdot \frac{\vec{R}}{R^3}) = (\vec{m} \nabla) \frac{\vec{R}}{R^3}$$

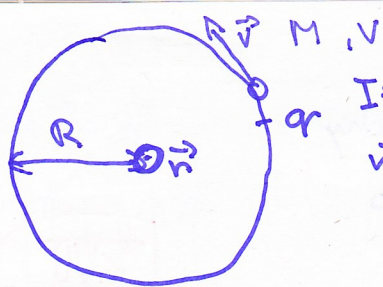
$$\vec{B} = \frac{\mu_0}{4\pi} \left( \frac{\vec{m} \cdot \vec{R}}{R^3} \right)$$

$$E = -\nabla \varphi$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \left[ \frac{3(\vec{m} \cdot \vec{R}) \vec{R}}{R^5} - \frac{\vec{m}}{R^3} \right]$$







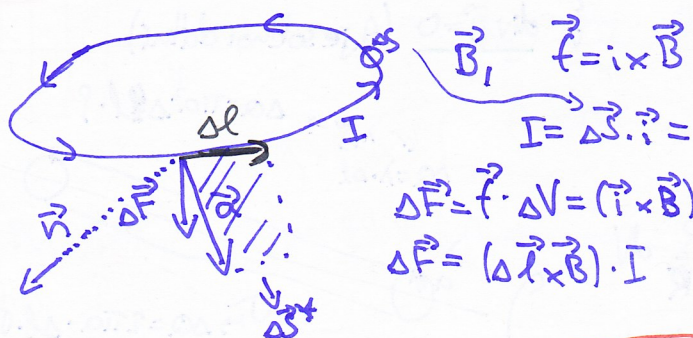
$$I = \frac{\Delta Q}{\Delta t} = \frac{qV}{2\pi R}$$

$$\vec{m} \Rightarrow m = \pi R^2 \cdot I = \frac{RqV}{2}$$

moment hybnosti  
 $|\vec{L}| = |m(\vec{R} \times \vec{v})| = mRv$

$$\gamma = \frac{m}{L} = \frac{q}{2m}$$

$\gamma = \frac{q}{2m} \rightarrow$  gyromagnetický poměr



$$\vec{f} = i \times \vec{B}$$

$$I = \Delta \vec{S} \cdot \vec{i} =$$

$$\Delta \vec{F} = \vec{f} \cdot \Delta V = (\vec{i} \times \vec{B}) \cdot \Delta S \cdot \Delta l$$

$$\Delta \vec{F} = (\Delta \vec{l} \times \vec{B}) \cdot I$$

$$\Delta A = \Delta \vec{F} \cdot \vec{a} = I \vec{a} \cdot \Delta \vec{l}$$

$$\Delta A = I \cdot (\underbrace{\vec{a} \times \Delta \vec{l}}_{\vec{s}^*}) \cdot \vec{B}$$

$$\Delta A = I \cdot \Delta \vec{S}^* \cdot \vec{B} = I \cdot \Delta \Phi$$

$$\Phi = \oint \vec{B} \cdot d\vec{S} = 0$$

$$\Phi_m = \Phi_2 - \Phi_1$$

$$A = I \cdot (\Phi_2 - \Phi_1)$$

$\hookrightarrow$  rozdíl práce po translaci

$$\Phi_1 = \int_{S_1} \vec{B} \cdot d\vec{S} \quad \Phi_2 = - \int_{S_2} \vec{B} \cdot d\vec{S}$$

$$W_m = -I \cdot \Phi$$

$$\Phi = \vec{B} \cdot \vec{S}$$

$$\vec{F} = (m \nabla) \vec{B}$$

XVIII



# Magnetické pole v látkovém prostředí (2.1).

$$\oint \vec{H} d\vec{l} = I \quad [A/m] \rightarrow H$$

↳ vektor intenzity magnetického pole

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

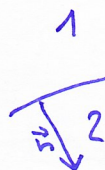
$$\vec{P}_m = \mu_0 \vec{M}$$

↳ vektor magnetické polarizace

$$\vec{n} \times (\vec{B}_1 - \vec{B}_2) = \mu_0 \vec{j}$$

$$\vec{j}_m = \vec{M} \times \vec{n}$$

$$\vec{j}_m = \text{rot } \vec{M}$$



v látkovém prostředí:

$$\vec{n} \times (\vec{B}_1 - \vec{B}_2) = \mu_0 (\vec{j} + \vec{j}_m)$$

$$\vec{n} \times (\vec{H}_1 - \vec{H}_2) = \vec{j}$$

## Materiálové vztahy

$$\vec{M} = f(\vec{H})$$

$$\vec{M} = \chi_m \vec{H} \rightarrow \text{magnetická susceptibilita}$$

$$\vec{P}_m = \mu_0 \chi_m \vec{H}$$

$\chi_m < 0$  ... diamagnetické látky ( $10^{-4} - 10^{-3}$ )

$\chi_m > 0$  ... paramagnetické látky ( $10^{-3} - 10^{-4}$ )

$\chi_m$  nelze jednoznačně stanovit ... feromagnetické

Larmorova precese :  $\omega = \gamma \cdot B$

↳ gyromagnetický poměr

$$\vec{m} = \gamma \cdot \vec{L}$$

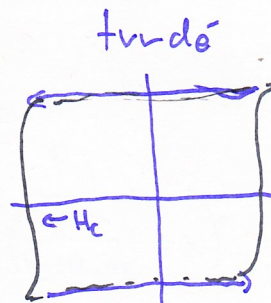
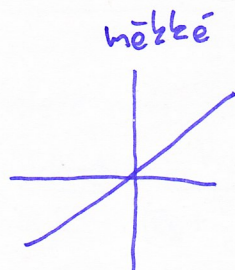
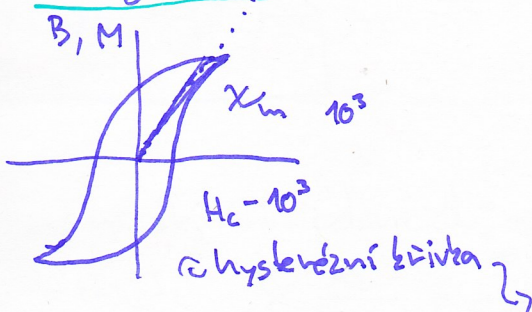
$$\hbar = \frac{h}{2\pi}$$

$$\mu_B = \frac{1e}{2m_e} \cdot \hbar \quad \dots \text{orbitální}$$

$$\rightarrow \text{Bohrův magneton} \rightarrow \mu_B^s = \frac{e}{m_e} \cdot \hbar \quad \dots \text{spinový} \quad (\approx 10^{-24})$$

na magnetických jerech se nejvíce podílí elektrony. (vlastnostech látky)

## Feromagnetické l.



feromagnetické l.  $\rightarrow \text{Fe}_3\text{O}_4$  (magnetit)  $\rightarrow \uparrow\uparrow\uparrow \uparrow\uparrow\uparrow$  (dobromady)

antiferomagnetické l.  $\rightarrow \uparrow\downarrow\uparrow\downarrow$

$$\chi_m = \frac{C}{T - T_c}$$

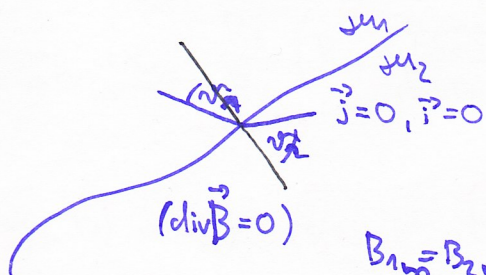
$$T > T_c$$

$$\vec{M} = \chi_m \cdot \vec{H}$$

$$\vec{B} = \mu_0 \vec{H} + \mu_0 \chi_m \vec{H}$$

$$\vec{B} = \mu_0 (1 + \chi_m) \cdot \vec{H}$$

permeabilita prostředí  $\mu_0 \cdot \mu_r = \mu$



$$B_{1n} = B_{2n}$$

$$H_{1t} = H_{2t}$$

$$\oint \vec{H} d\vec{l} = 0$$

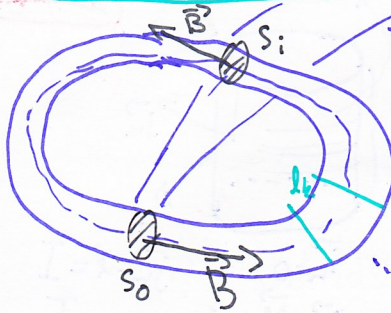
$$\text{rot } \vec{H} = 0$$

$$\mu_2 \gg \mu_1$$

$$\frac{\tan \alpha_1}{\tan \alpha_2} = \frac{\mu_1}{\mu_2}$$



## Magnetický obvod



$$\Phi = \text{konst.}$$

$$\Phi = \int_S \vec{B} \cdot d\vec{S}$$

→ magnetický tok je stejný ve všech bodech trubice

$$\oint_l \vec{H} \cdot d\vec{l} = I \rightarrow \text{magnetomotivní napětí (proud)}$$

↳ nové značení  $\mathcal{F}$

$$\oint_l \vec{H} \cdot d\vec{l} = w_k \rightarrow \text{spád magnetického potenciálu}$$

$$H = \frac{B}{\mu_k}$$

pro křivé prostředí

$$H = \frac{B}{\mu_0} \quad B = \frac{\Phi}{\Delta S}$$

platí pro vakuum

$$w_k = \Phi \int_l \frac{dl}{\Delta S \mu_k}$$

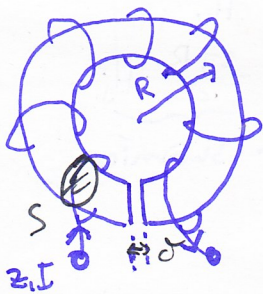
$$R_{mk} = \int_l \frac{dl}{\Delta S \mu_k}$$

↳ magnetický odpor

$$w_k = \Phi \cdot R_{mk}$$

$$\mathcal{F} = \sum_{i=1}^N \oint_l \vec{H} \cdot d\vec{l} =$$

$$= \Phi \cdot \sum_{i=1}^N w_i = \Phi (R_{m1} + R_{m2} + \dots + R_{mN})$$



$$\mathcal{F} = z \cdot I$$

$B_j B_v$  → prádný prostor  
↳ jedné

$S, \sigma$  malé

$$R_{mj} = \frac{2\pi R - \sigma}{S \mu_j}$$

$$\mu = \mu_r \cdot \mu_0$$

$$R_{mv} = \frac{\sigma}{S \mu_0}$$

$\Phi$  je konst.

$$\Phi = B_j \cdot S = B_v \cdot S$$

$$B_j = B_v = B$$

$$\frac{B \cdot S}{S \mu_j} = \frac{I \cdot z}{2\pi R - \sigma + \frac{\sigma}{S \mu_0}}$$

pro malé  $\sigma$  můžeme zanedbat

$$B = \frac{I \cdot z}{2\pi R + \frac{\sigma}{S \mu_0}} = \frac{I \cdot z \cdot \mu_r \cdot \mu_0}{2\pi R + \sigma} = B$$

Také lze spočítat →  $H_v = \frac{B}{\mu_0}$

↳ v měřiče je větší intenzita

$$H_j = \frac{B}{\mu_0 \mu_r}$$

## Magnetostatické pole

$$\oint \vec{H} \cdot d\vec{l} = 0, \text{ rot } \vec{H} = 0 \quad (\text{zdrojem mag. pole jsou zmag. tělesa} \rightarrow \vec{M}(\vec{r}))$$

$$\vec{B} = \mu_0 \vec{H} \text{ m v tělesech} \rightarrow \vec{B} = \mu_0 \vec{H} + \mu_0 \vec{M}$$

$$q_m = \frac{\mu_0}{4\pi} \cdot \frac{\vec{r} \cdot \vec{R}}{R^3} ; \vec{B} = -\nabla \varphi_m \quad (\text{magn. dipól})$$

$$M(\vec{r}) \quad \rho_m = -\text{div } \vec{M}$$

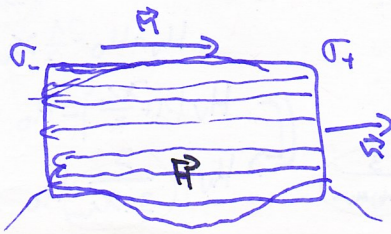
$$\sigma_m = \vec{M} \cdot \vec{n}$$

$$\varphi_m^* = \frac{1}{4\pi} \left[ \int_V \frac{\rho_m}{R} dV + \int_S \frac{\sigma_m}{R} dS \right]$$

$$\vec{H} = -\nabla \varphi_m^*$$

$$\vec{B} = -\mu_0 \text{ grad } \varphi_m^*$$

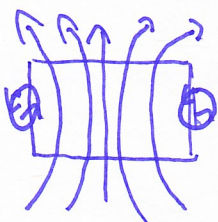
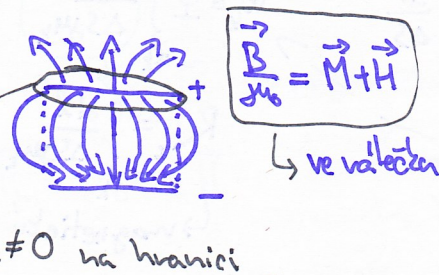
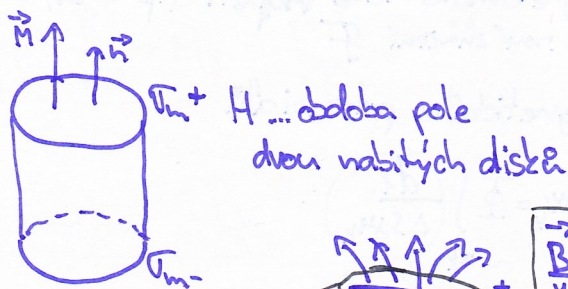
platí pro  $\vec{B}$  mimo tělesa



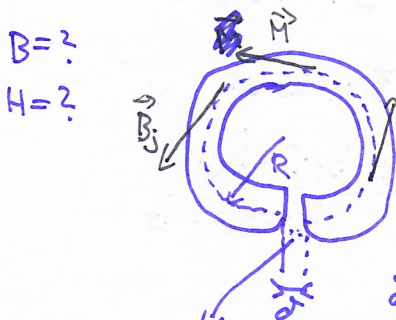
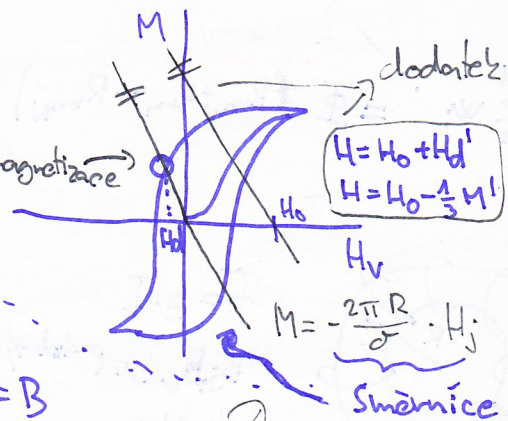


# Magnetostatika (2)

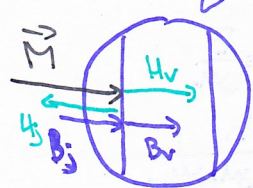
$\text{rot } H = 0 \quad (\vec{r} = 0), \quad \forall \dots \vec{M}(\vec{r})$   
 $\text{rot } B \neq 0$   
 $\rho_m \dots \rho_m = -\text{div } \vec{M}$   
 $\sigma_m \dots \sigma_m = \vec{r} \cdot \vec{M}$



## Demagnetizační pole (ob: depolarizační pole) bod demagnetizace



$\Phi = \text{konst.} \quad \oint \vec{H} d\vec{l} = 0$   
 $\Phi = \vec{B} \cdot \vec{S}$   
 $\rightarrow \parallel \text{konst.}$   
 $\text{konst.}$   
 $B_j = B_v = B$   
 $H_v = \mu_0 B_v$



$\oint \vec{H} d\vec{l} + \oint \vec{H} d\vec{l} = 0$   
 $H_j(2\pi R - \sigma) + H_v \cdot \sigma = 0$

$\vec{B} = \mu_0 \vec{H}_j + \mu_0 \vec{M}$   
 $\mu_0 \vec{H}_v = \mu_0 \vec{H}_j + \mu_0 \vec{M}$   
 $H_v = H_j + M$  (dosadím)  
 $H_j = -\frac{\sigma}{2\pi R - \sigma} \cdot H_v$   
 $M = H_v - H_j$   
 $M = -H_j \left( \frac{2\pi R - \sigma}{\sigma} \right) - H_j$   
 $M = -H_j (2\pi R + 1 - 1)$   
 $M = -\frac{2\pi R}{\sigma} H_j$

## Koule v homog. mag. poli

Tělesa ve tvaru elipsoidu se homogenně zmagnetují.

$H_{dx} = -N_x \cdot M_x \quad \vec{M} (M_x, M_y, M_z)$

konle:  $N_x = N_y = N_z = \frac{1}{3}$

vallec:  $N_x + N_y = \frac{1}{2}; N_z = 0$   
 $M_z \neq 0$

Koule:  $\vec{H}_v = \vec{H}_0 + \vec{H}_d$   
 $H_v = H_0 - \frac{M}{3}$   
 $H_v = H_0 - \frac{1}{3} \chi_m H_v$   
 $H_v (1 + \frac{\chi_m}{3}) = H_0$   
 $H_v = \frac{3}{3 + \chi_m} H_0$



# Elektromagnetická indukce $\rightarrow$ Weber

$$\mathcal{E}_F = - \frac{d\psi}{dt}$$

$\rightarrow$  elektromotorické napětí

$$\Phi [Wb] [V \cdot s]$$

$$\psi = \sum_i \Phi_i$$

$\rightarrow$  celkový mag. bl

$$\Phi = \int_S \vec{B} d\vec{S}$$

$$\Phi = \int_S \vec{B} d\vec{S} = \int_B \text{rot} \vec{A} d\vec{S} = \oint_l \vec{A} d\vec{l}$$

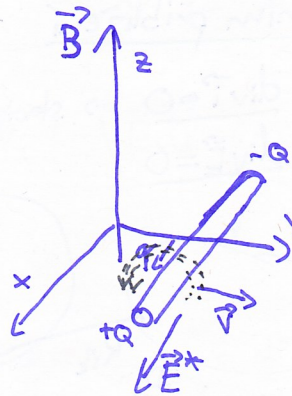
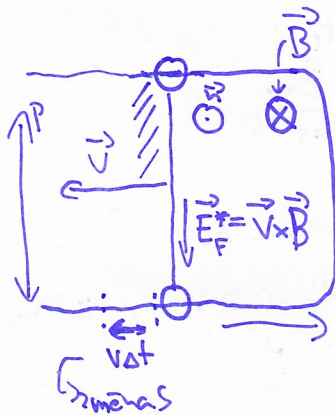
$$\mathcal{E}_F = - \frac{d}{dt} \oint \vec{A} d\vec{l}$$

$$\mathcal{E}_F = - \oint \frac{\partial \vec{A}}{\partial t} d\vec{l}$$

## Elektromagnetická indukce (2)

M. Faraday (1831)

$$(E_F) \mathcal{E}_F, R, I(t) = \frac{\mathcal{E}_F(t)}{R}$$



$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$\vec{E}^* = \vec{v} \times \vec{B}$$

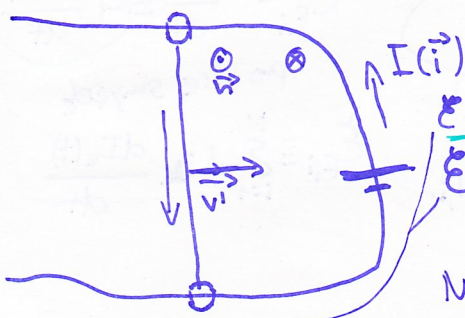
$$\vec{E} = -\vec{v} \times \vec{B}$$

$$\mathcal{E}_F = \oint \vec{E}_F^* d\vec{l} = v \cdot B \cdot p$$

$$\Delta \psi = -B \cdot p \cdot v \cdot \Delta t$$

$\rightarrow$

$$\mathcal{E}_F = - \frac{\Delta \psi}{\Delta t} = v \cdot B \cdot p$$



$$-\frac{\mathcal{E}'_F}{I}$$

$$\mathcal{E} \cdot I = RI^2 + Bvp \cdot I$$

$$\mathcal{E}' \cdot I = RI^2 + N_m$$

$$N_m = \vec{F} \cdot \vec{v}$$

$$N_m = B \cdot p \cdot I \cdot v$$

$$\vec{f} = i \times \vec{B}$$

$$\vec{F} = \vec{f} \cdot v$$

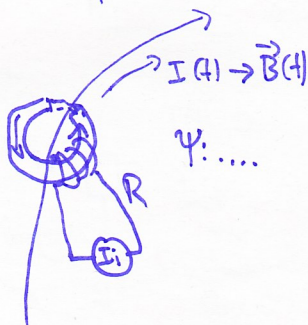
$$\mathcal{E}'_F = \oint \vec{E}_F^* d\vec{l} = Bv'p$$

$$p.s. (S = \frac{I}{i})$$

$$|\vec{F}| = i \cdot B \cdot p \cdot \frac{I}{i}$$

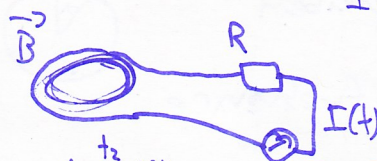
$$(\mathcal{E} + \mathcal{E}'_F) I = RI^2$$

kleštový ampérmetr:



princip "FLUXMETR"-u

$$I(t) = \frac{\mathcal{E}_F}{R}$$



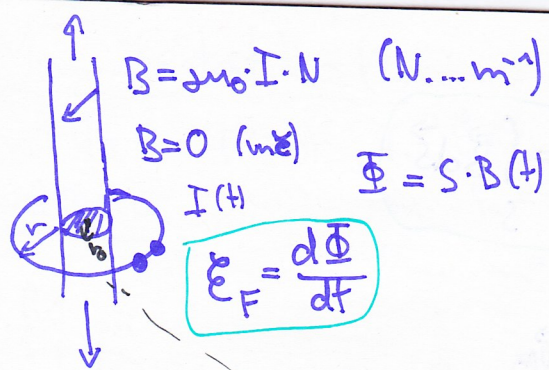
$$q = \int_{t_1}^{t_2} I(t) dt = \frac{-1}{R} \int_{t_1}^{t_2} \frac{d\psi}{dt} dt$$

$$q = \frac{-1}{R} \int_{\psi(t_1)}^{\psi(t_2)} d\psi = \frac{\psi_1 - \psi_2}{R}$$

$$\mathcal{E}_F = - \frac{d\psi}{dt}$$

XXI.

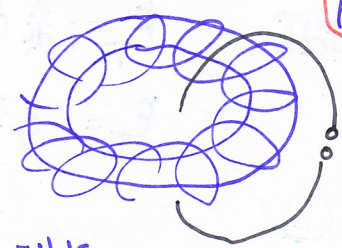




místo  $\vec{B}$ ... stačí znát  $\vec{A}(t)$  podle větší smyčky

$\Phi = \int \vec{B} d\vec{S} = \oint \vec{A} d\vec{l}$

$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{j}}{R} dV$



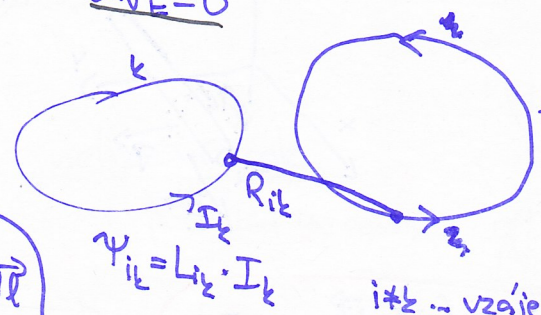
$\vec{A}_H(\vec{r}) = \frac{1}{2} \vec{B} \times \vec{r}^2$   
 $A(\vec{r}) = \frac{1}{2} (\vec{B} \times \vec{r}) \cdot \frac{r_0^2}{r^2}$   
 $r > r_0$   
 $r < r_0$

Elektrický obvod v kvazistacionárním přiblížení

$\Psi_i(\Phi) \quad \Psi \propto I$

Induktance  $\Psi = L \cdot I$

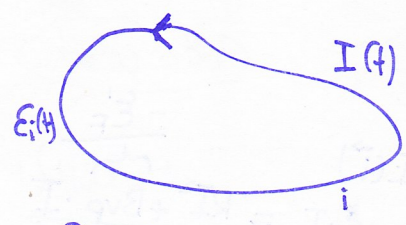
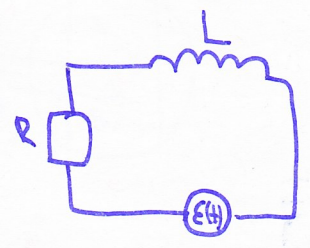
$\text{div } \vec{I} = 0 \rightarrow \text{stacionární}$   
 $\text{div } \vec{E} = 0$



$\Psi_i = \sum_{k=1}^N \Psi_{ik}$   
 $\Psi_i = \sum_{k=1}^N \Psi_{ik}$

$i \neq k$  ... vzájemná indukčnost  
 $L_{ii}$  ... v případě jediné smyčky  $L_{ii}$

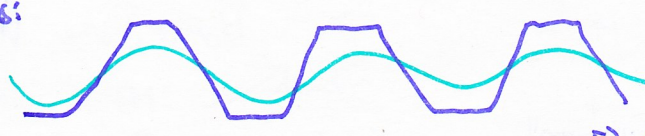
$L_{ik} = L_{ki}$   
 $\Psi_{ik} = \oint \vec{A}_k d\vec{l}_i \quad \vec{A}_k = \frac{\mu_0}{4\pi} \oint \frac{I_k}{R} d\vec{l}_k$   
 $\Psi_{ik} = \frac{\mu_0}{4\pi} I_k \oint \oint \frac{d\vec{l}_k d\vec{l}_i}{R_{ik}}$   
 $\Psi_{ik} = L_{ik} \cdot I_k$



$\mathcal{E}_{F,i} = -\frac{d\Psi_i}{dt} = -L \frac{dI}{dt}$   
 po více smyčkách  
 $\mathcal{E}_{F,i} = \sum_{k=1}^N -L_{ik} \frac{dI_k(t)}{dt}$

celkový  $R_{c,i} \cdot I_i = \mathcal{E}_i(t) + \mathcal{E}_{F,i}$   
 $R_c I = \mathcal{E}(t) - L \frac{dI}{dt}$

Pokus:

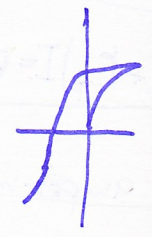


$\rightarrow$  nikoliv sin nebo cos

není harmonický průběh



$\alpha = \cos \omega t$



$\rightarrow$  vyšší harmonická frekvence



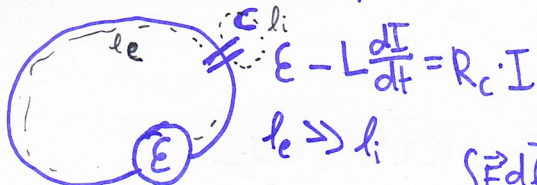
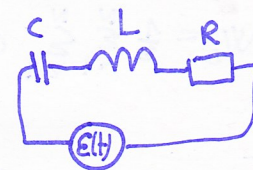
# "Kvazistacionární obvody" (2)

XXII

$$\text{div } \vec{I} = 0 \quad c \cdot f_1 \cdot \lambda = c \cdot T$$

$\oint \vec{E} d\vec{l} = 0 \rightarrow D \approx \lambda \rightarrow$  nemůžeme použít toto přiblížení  
charakteristický rozměr telefonů

$D \ll \lambda \rightarrow$  můžeme použít metodu soustředěných parametrů



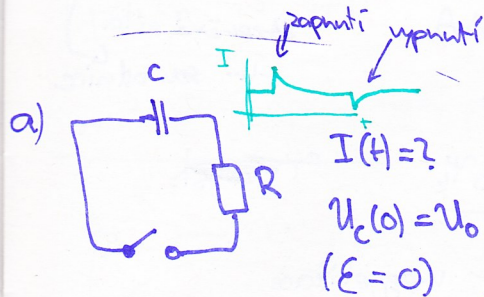
$$\oint_{l_i} \vec{E} d\vec{l} + \oint_{l_e} \vec{E} d\vec{l} = 0 \quad \frac{S}{S} \int \frac{i}{r} dl = \int (E + E^*) dl$$

$$\oint_{l_i} \vec{E} d\vec{l} = U_c(t) = \frac{Q(t)}{C} \rightarrow I \cdot R_c = - \oint_{l_i} \vec{E} d\vec{l} + E(t) - L \frac{dI(t)}{dt}$$

$$I(t) \cdot R_c = - \frac{Q(t)}{C} + E(t) - L \frac{dI(t)}{dt}$$

$$L \frac{d^2 I(t)}{dt^2} + I(t) \cdot R + \frac{Q(t)}{C} = E(t) \quad \left| \frac{d}{dt} \rightarrow a \right) L \frac{d^2 I}{dt^2} + R \frac{dI}{dt} + \frac{I}{C} = \frac{dE(t)}{dt}$$

$$\underbrace{\Delta \Psi \cdot I}_{W_L} + \underbrace{\Delta Q \cdot U}_{\Delta W_C} = \Delta W_E$$



$$W_L = \Psi \cdot \Delta I$$

$$b) LI \frac{dI}{dt} \Delta t + I^2 R \cdot \Delta t + \frac{Q \cdot \Delta Q}{C} = E I \cdot \Delta t$$

$$\frac{d}{dt} \left( \frac{1}{2} LI^2 \right) \Delta t + I^2 R \cdot \Delta t + \frac{Q}{C} \left( \frac{dQ}{dt} \cdot \Delta t \right) = E I \cdot \Delta t$$

energie mag. pole  
cívky, když ji  
prochází proud I.

$$\frac{d}{dt} \left( \frac{1}{2} \frac{Q^2}{C} \right) \Delta t = \Delta W_C$$

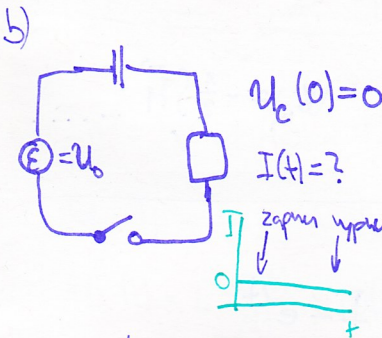
časová změna E  
na nabitém kondenzátoru

$$\Delta W_C = U_C \cdot \Delta Q$$

$\rightarrow$  proud exponenciálně  
klesá s časem

$$L \frac{d^2 I}{dt^2} + R \frac{dI}{dt} + \frac{I}{C} = U_0 \cos(\omega t)$$

pro střídavý proud

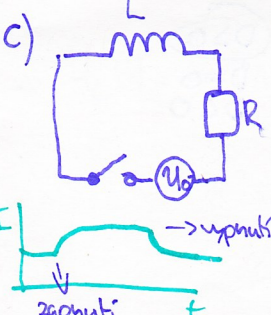


$$L \frac{d^2 I}{dt^2} + R \frac{dI}{dt} + \frac{I}{C} = 0$$

$$I_0 \cdot \cos(\omega t + \varphi)$$

amplituda  $(\omega L, \frac{1}{\omega C}, R)$

přepočty na impedanci...



$$I(t) = 0 \quad I(t \rightarrow \infty) = \frac{U_0}{R}$$

$$L \frac{dI}{dt} + IR = U_0$$

$\rightarrow$  indikátor  
rezonance v  
obvodu?  
 $\Rightarrow$  maximální  
proud

$\rightarrow$  fázový posuv nulový



# El. obvod, magnetické pole v kvazistacionárním přiblížení

$\Delta W$   $U_c \Delta Q_c$   $I \Delta \Psi$  (LI =  $\Psi$ )

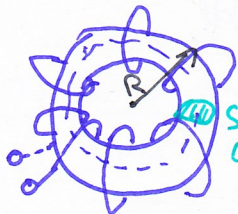
$\Delta W_m = L \cdot I \cdot \Delta I \dots dW_m = LI dI$

$W_m = \int_0^I LI dI = \frac{1}{2} LI^2 = \frac{1}{2} \cdot \Psi \cdot I = \sum_{l=1}^N \Psi_l \cdot I$

$W_c = \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N C_{ik} \varphi_{oi} \cdot \varphi_{oj}$

podle principu superpozice:  $\frac{1}{2} \sum_{l=1}^N \sum_{j=1}^N I_l \cdot I_j \cdot L_{lj} = W_m$

## Energie, toroidální cívka



$W_m = \frac{1}{2} \cdot \Psi \cdot I$

$\oint \vec{H} d\vec{l} = I_c \rightarrow 2\pi R \cdot H = N \cdot I$

$B = \mu \cdot I \cdot N \cdot \frac{1}{2\pi R}$

$W_m = \frac{1}{2} N \cdot B \cdot S \cdot \frac{2\pi R H}{I} = \frac{\vec{B} \cdot \vec{H}}{2} \cdot (2\pi R \cdot S)$   
 → jsou kolmé  
 Objem jádra (V)

$W_m = w_m \cdot V$

→ hustota energie mag. pole (v jádře)

$W_m = \int_V \left( \frac{\vec{H} \cdot \vec{B}}{2} \right) dV$

$\frac{LI^2}{2} = \int_V \left( \frac{\vec{H} \cdot \vec{B}}{2} \right) dV$

$\Psi = L \cdot I$

vztah pro indukčnost toroidální cívky

$S \cdot N \cdot B = \mu \cdot I \cdot N^2 \cdot \frac{S}{2\pi R} = L \cdot I$

$\sum_k \mathcal{E}_k \cdot I_k \cdot \Delta t = \sum_k R_c I_k^2 \cdot \Delta t + \sum_k I_k \frac{d\Psi_k}{dt} \cdot \Delta t$

balance energie

$I_k \Delta \Psi_k = \Delta W_m$

$\Delta W = \Delta W_m + \Delta A$

$W_m = \frac{1}{2} I \Psi$

$\Delta W_m = \frac{1}{2} I \Delta \Psi_k$

podle  $\vec{E}$

$\Delta A = G_i \Delta \xi_i$

zdeňová síla  
-ll- souřad.

$\Psi = \text{konst.} \quad G_i = \frac{\partial W_m}{\partial \xi_i} \Big|_{\Psi = \text{konst.}}$

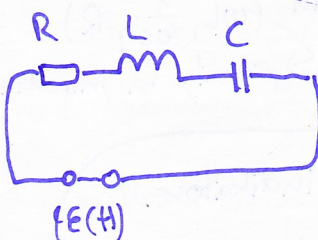
$G_i = \frac{\partial W_m}{\partial \xi_i} \Big|_{I_k = \text{konst.}}$

$\vec{W} = \vec{M} \cdot \vec{B}$  vektor magnetizace

$\vec{F} = (\vec{\nabla} \cdot \vec{B}) \vec{B}$

$W = - \int \vec{M} \cdot \vec{B}_0 dV$

$W_m = - \frac{1}{2} \int_V \vec{M} \cdot \vec{B}_0 dV$



$C \dots Q_c(0) \neq 0$

$U_c(t=0) = U_c$

$L \frac{d^2 I}{dt^2} + R \frac{dI}{dt} + \frac{I}{C} = 0$

$I(t) = k_1 e^{\lambda_1 t} + k_2 e^{\lambda_2 t}$

$I = e^{\lambda t}$

$L \lambda^2 e^{\lambda t} + R \lambda e^{\lambda t} + \frac{e^{\lambda t}}{C} = 0$

$D = R^2 - \frac{4L}{C}$

$\begin{matrix} D > 0 \\ D = 0 \\ D < 0 \end{matrix}$

$L \lambda^2 + R \lambda + \frac{1}{C} = 0$   
 $\lambda_{1,2} = \frac{-R \pm \sqrt{R^2 - \frac{4L}{C}}}{2L}$

$\lambda_{1,2} = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{CL}}$

$I(t) = k_1 e^{-\frac{R}{2L}t} \left( k_1 e^{\frac{\sqrt{D}}{2L}t} + k_2 e^{-\frac{\sqrt{D}}{2L}t} \right)$



Poč. podmínky  $I(0) = 0 \Rightarrow k_1 = -k_2$  ;  $\frac{R}{2L} = \gamma$   $L \cdot \frac{dI}{dt} = U_c(0)$

$$I(t) = k_1 e^{-\frac{R}{2L}t} + (e^{\frac{\sqrt{D}}{2L}t} - e^{-\frac{\sqrt{D}}{2L}t})$$

$$I(t) = 2k_1 e^{-\gamma t} \sinh\left(\frac{\sqrt{D}}{2L}t\right)$$

$$\left. \frac{dI}{dt} \right|_{t=0} = 2k_1 (-\gamma) e^{-\gamma t} \underbrace{\sinh(0)}_{=0} + 2k_1 e^{-\gamma t} \underbrace{\cosh\left(\frac{\sqrt{D}}{2L}t\right)}_{=1} \cdot \frac{\sqrt{D}}{2L}$$

$$\frac{U_c(0)}{L} = 2k_1 \frac{\sqrt{D}}{2L}$$

$$k_1 = \frac{U_c}{\sqrt{D}}$$

$$I(t) = \frac{2U_c}{\sqrt{D}} \cdot e^{-\gamma t} \cdot \sinh\left(\frac{\sqrt{D}}{2L}t\right)$$

$D < 0$   $\lambda_{1,2} = -\frac{R}{2L} \pm \sqrt{\gamma^2 - \omega_0^2}$

$$\omega_0^2 = \frac{1}{LC}$$

$$\lambda_{1,2} = -\frac{R}{2L} \pm i\omega$$

$$I(t) = 2ik_1 e^{-\gamma t} \left( \frac{e^{i\omega t} - e^{-i\omega t}}{2i} \right) = 2ik_1 e^{-\gamma t} \sin(\omega t)$$

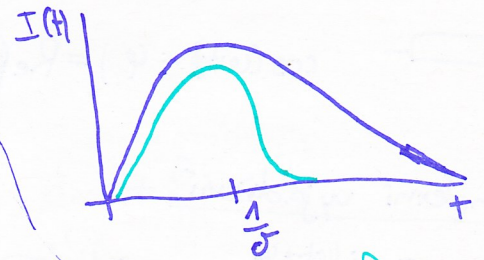
$$i = e^{i\varphi}$$

$$e^{i\varphi} = \cos \varphi + i \sin \varphi$$

$$\varphi = \frac{\pi}{2}$$

$$I(t) = 2k_1 e^{-\gamma t} \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$I(t) = \frac{U_c(0)}{\omega L} e^{-\gamma t} \cdot \sin(\omega t)$$



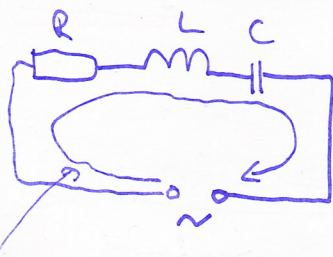
$$F = \int_V (\vec{M} \cdot \nabla) \vec{B} dV$$

$D=0$   $A \cdot t \cdot e^{\lambda t}$

$$I(t) = A \cdot t \cdot e^{-\frac{R}{2L}t} \quad L \cdot \left. \frac{dI}{dt} \right|_{t=0} = U_c$$

$$I(t) = \frac{U_0}{L} \cdot t \cdot e^{-\frac{R}{2L}t}$$

→ mezní aperiodický průběh



$$2\pi f \quad f = \frac{1}{T}$$

$$U(t) = U_0 \cos(\omega t + \varphi)$$

$$\vec{B} \cdot \vec{S}$$

$$\lambda = \omega t$$

$$\Psi = B \cdot S \cdot \cos(\omega t + \varphi)$$

- efektivní hodnota  
- účinník

$$I(t) = I_0 \cdot \cos(\omega t + \varphi_I)$$

$$F(t) = \sum_{k=-\infty}^{\infty} c_k e^{ik \cdot \frac{1}{T} \cdot 2\pi t}$$

superpozice harmonických funkcí

$$U_R(t) = R \cdot I_0 \cos(\omega t + \varphi_I)$$

$$U_L(t) = L \frac{dI(t)}{dt} = \omega L I_0 (-\sin(\omega t + \varphi_I)) = \omega L \cdot I_0 (\cos(\omega t + \varphi_I + \frac{\pi}{2}))$$

$$U_C(t) = \frac{1}{C} \int I_0 \cos(\omega t + \varphi_I) = \frac{1}{\omega C} I_0 \sin(\omega t + \varphi_I) = \frac{I_0}{\omega C} \cos(\omega t + \varphi_I - \frac{\pi}{2})$$



# Střídavé obvody (2)

komplexní symbolika, řešení obvodu



$$I_L(t) = I_{0L} \cos(\omega t)$$

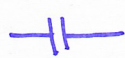
$$U_L(t) = U_{0L} \cos(\omega t + \frac{\pi}{2})$$

$$\varphi_I = 0$$

→ napětí předchází proud

IMPEDANCE

$$U_{0L} = I_{0L} \cdot Z_L$$



$$I_C(t) = I_{0C} \cos(\omega t)$$

$$U_C(t) = U_{0C} \cos(\omega t - \frac{\pi}{2}) \rightarrow \text{proud předchází napětí}$$

$$U_{0C} = I_{0C} \cdot Z_C$$



$$\cos(\omega t + \varphi) = \text{Re}[\cos(\omega t + \varphi) + i \sin(\omega t + \varphi)] = \text{Re} e^{i(\omega t + \varphi)} = \underbrace{e^{i\omega t}}_{\text{e}^{i\omega t}} \cdot \underbrace{e^{i\varphi}}_{\text{e}^{i\varphi}}$$

## Komplexní vyjádření

$$\hat{I}(t) = I_0 e^{i(\omega t + \varphi)} = I_0 e^{i\omega t} \cdot e^{i\varphi}$$

$$\hat{U}(t) = U_0 e^{i\omega t} = U_0 e^{i\omega t} \cdot e^{i\varphi}$$

komplexní amplituda :  $\bar{I} = I_0 e^{i\varphi_I}$   
 $\bar{U} = U_0 e^{i\varphi_U}$

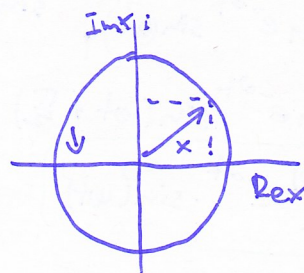
## Ohmův zákon pro střídavé obvody

$$\bar{U}_R = R \bar{I}_R$$

$$\bar{U}_L = \omega L \cdot I_{0L} \cdot e^{i\frac{\pi}{2}} = i\omega L \cdot I_{0L} = \bar{Z}_L \cdot I_{0L} = \bar{Z}_L \cdot \bar{I}_L$$

$$\bar{U}_C = \frac{1}{\omega C} \cdot I_{0C} \cdot e^{-i\frac{\pi}{2}} = -\frac{i}{\omega C} \cdot I_{0C} = \left(\frac{1}{i\omega C}\right) \cdot I_{0C} = \bar{Z}_C \cdot \bar{I}_C$$

komplexní impedance kapacity



$$\bar{Z} = Z_0 e^{i\varphi} = Z_{Re} + i Z_{Im}$$

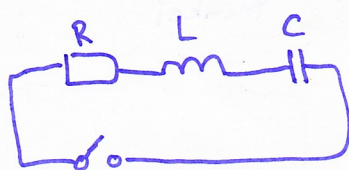
$$Z_0^2 = Z_{Re}^2 + Z_{Im}^2$$

Kirchhoffova pravidla:  $\sum_{j=1}^N \text{Re} \hat{I}_j(t) = \text{Re} \sum_{j=1}^N \hat{I}_j(t) \Rightarrow \sum_{j=1}^N \hat{I}_j(t) = 0 \Rightarrow \sum_{j=1}^N \bar{I}_j = 0$

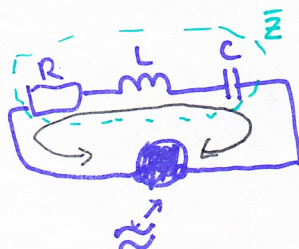
$$\text{II.) } \sum_{j=1}^N \text{Re} \hat{U}_j(t) = \sum_{k=1}^M \text{Re}(\bar{Z}_k \cdot \hat{I}_k(t))$$

$$\text{Re} \sum_j \bar{U}_j e^{i\omega t} = \sum_k \bar{Z}_k \bar{I}_k e^{i\omega t} \Rightarrow \bar{U}_j = U_{0j} \cdot e^{i\varphi_j}$$

Admittance → převracení hodnoty impedance



$$Q(\omega) = Q$$



$$U(t) = U_0 \cdot \cos \omega t$$

$$I(t)$$

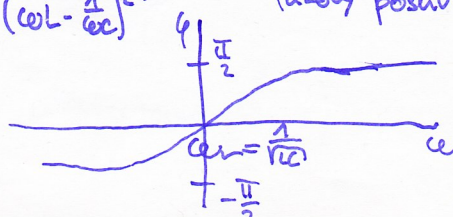
$$\bar{I} = \frac{\bar{U}}{\bar{Z}} ; \bar{Z} = R + i(\omega L - \frac{1}{\omega C})$$

$$Z_0 = \sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}$$

fázový posuv  $\Rightarrow \tan \varphi$

$$\bar{U}_C = \bar{Z}_C \cdot \bar{I}$$

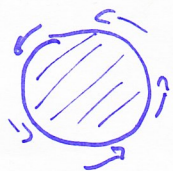
$$\bar{U}_L = \bar{Z}_L \cdot \bar{I}$$





$$\mathcal{E}_F = - \frac{d\psi}{dt} - \int \frac{\partial \vec{B}}{\partial t} d\vec{S} = \oint \vec{E}_i d\vec{l} \quad \oint \vec{E}_i d\vec{l} \neq 0$$

$$\vec{F} = Q[\vec{E} + \vec{v} \times \vec{B}]$$



$$\Delta t \cdot I = Q$$

$$\oint \vec{E}_i d\vec{l} \neq 0$$

$$\text{pro } Q=1$$

$$\hookrightarrow \oint \vec{E}_i d\vec{l} = \mathcal{E}_F$$

$$\int \text{rot} \vec{E} d\vec{S} = - \int \frac{\partial \vec{B}}{\partial t} d\vec{S}$$

$$\int (\text{rot} \vec{E} + \frac{\partial \vec{B}}{\partial t}) d\vec{S} = 0$$

$$\boxed{\text{rot} \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0}$$

$\mathcal{E}_F \rightarrow$  Faradayovo indukované napětí

$$\text{div} \vec{D} = \rho$$

$$\text{rot} \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad \text{div} \vec{B} = 0$$

$$\text{rot} \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t}$$

$\hookrightarrow$  Ampérův z.

rovnice kontinuity

$$\text{div} \vec{j} + \frac{\partial \rho}{\partial t} = 0$$

!\*

$$\text{div} \vec{j} + \frac{\partial}{\partial t} \text{div} \vec{D} = 0$$

$$\text{div} \left( \vec{j} + \frac{\partial \vec{D}}{\partial t} \right) = 0$$

Kvazistacionární přiblížení

$$\vec{j} \gg \frac{\partial \vec{D}}{\partial t}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

$$\frac{\partial \vec{D}}{\partial t} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \frac{\partial \vec{P}}{\partial t}$$

polarizační proud

$\hookrightarrow$  Maxwellův posuvný proud.

$\vec{E}, \vec{D}, \vec{B}, \vec{H}$  (12 neznámých)  $\Rightarrow$  8 rovnic

$\hookrightarrow$  doplníme o Materiálové vztahy:  $\vec{D} = \vec{D}(\vec{E})$   
 $\vec{H} = \vec{H}(\vec{B})$  } 6 rovnic

$$> 8+6=14$$

$$\text{div} (\text{rot} \vec{E}) = \frac{\partial}{\partial t} (\text{div} \vec{B})$$

$$\frac{\partial}{\partial t} (\text{div} \vec{B}) = 0$$

$$\frac{\partial}{\partial t} (\text{div} \vec{B} = 0)$$

$$0 = \text{div} \vec{j} + \frac{\partial}{\partial t} (\text{div} \vec{D})$$

$$0 = -\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial t} (\text{div} \vec{D})$$

$$0 = \frac{\partial}{\partial t} (\text{div} \vec{D} - \rho)$$

Elektromagnetické potenciály

$$\vec{B} = \text{rot} \vec{A}$$

$\hookrightarrow$  vektorový potenciál

$$\text{rot} \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\text{rot} \vec{E} = - \frac{\partial}{\partial t} \text{rot} \vec{A}$$

$$\Rightarrow \vec{E}_i = - \frac{\partial \vec{A}}{\partial t}$$

$$\text{rot} \left( \vec{E} + \frac{\partial \vec{A}}{\partial t} \right) = 0 \Rightarrow \boxed{\vec{E} + \frac{\partial \vec{A}}{\partial t} = - \text{grad} \varphi}$$

Maxw. R.  $\vec{D} = \epsilon \cdot \vec{E} \rightarrow$  předpokládám

##

$$\text{div} \vec{D} = \rho$$

$$\text{div} \vec{E} = \frac{\rho}{\epsilon}$$

$$\text{div} \left( -\text{grad} \varphi - \frac{\partial \vec{A}}{\partial t} \right) = \frac{\rho}{\epsilon}$$

$$-\Delta \varphi - \frac{\partial}{\partial t} (\text{div} \vec{A}) = \frac{\rho}{\epsilon}$$

XXV.



2. Ampérová 2. ( $\vec{B} = \mu_0 \vec{H}$ )

$$\text{rot } \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon \cdot \frac{\partial \vec{E}}{\partial t}$$

dosazením z minulé stránky

$$\rightarrow \text{rot rot } \vec{A} = \mu_0 \vec{j} + \mu_0 \epsilon \frac{\partial}{\partial t} (-\text{grad } \varphi - \frac{\partial \vec{A}}{\partial t})$$

$$-\Delta \vec{A} + \text{grad}(\text{div } \vec{A}) = \mu_0 \vec{j} + \mu_0 \epsilon (-\frac{\partial^2 \vec{A}}{\partial t^2}) - \text{grad} \frac{\partial \varphi}{\partial t} (\mu_0 \epsilon)$$

$$\Delta \vec{A} - \text{grad}(\text{div } \vec{A}) = -\mu_0 \vec{j} + \mu_0 \epsilon \frac{\partial^2 \vec{A}}{\partial t^2} + \text{grad} \frac{\partial \varphi}{\partial t} (\mu_0 \epsilon)$$

$$\Delta \vec{A} - \mu_0 \epsilon \frac{\partial^2 \vec{A}}{\partial t^2} = -\mu_0 \vec{j} + \underbrace{\text{grad}(\text{div } \vec{A} + \frac{\partial \varphi}{\partial t} \mu_0 \epsilon)}_{=0} \Rightarrow \text{div } \vec{A} = -\frac{\partial \varphi}{\partial t} \mu_0 \epsilon$$

Dosazení z předchozí stránky

$$\rightarrow -\Delta \varphi + \frac{\partial}{\partial t} (\mu_0 \epsilon \frac{\partial \varphi}{\partial t}) = \frac{\rho}{\epsilon}$$

$$\Delta \varphi - \mu_0 \epsilon \frac{\partial^2 \varphi}{\partial t^2} = -\frac{\rho}{\epsilon_0}$$

pro vakuum: (vlnová rovnice)

$$\Delta \vec{A} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{A}}{\partial t^2} = 0$$

$$\Delta \varphi - \mu_0 \epsilon_0 \frac{\partial^2 \varphi}{\partial t^2} = 0$$

$$\frac{1}{c^2} = \mu_0 \epsilon_0$$

$$c_0 = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\varphi' = \varphi - \frac{\partial \Delta}{\partial t} \quad \Delta = f(r, t)$$

$$A' = A + \nabla \Delta$$

Energie elektromagnetického pole

(hybnost se přeskakuje)

(Poyntingova věta)

$$\vec{f} = \rho(\vec{E} + \vec{v} \times \vec{B}) \quad \vec{v}(\vec{v} \times \vec{B}) = 0$$

$$n = \vec{f} \cdot \vec{v} = \vec{v} \cdot \rho \cdot \vec{E} = \vec{j} \cdot \vec{E}$$

$$\text{rot } \vec{H} = \vec{j} + \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$n = \vec{j} \cdot \vec{E} = \vec{E} \cdot \left\{ \text{rot } \vec{H} - \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} \right\}$$

$$\text{rot } \vec{E} + \mu \frac{\partial \vec{H}}{\partial t} = 0 \quad | \cdot \vec{H}$$

$$\vec{H} \cdot \text{rot } \vec{E} + \mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} = 0$$

$$n = \underbrace{\vec{E} \cdot \text{rot } \vec{H}}_{\vec{H} \cdot \text{rot } \vec{E}} - \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} - \mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t}$$

$$n = \vec{E} \cdot \vec{j} = -\text{div}(\vec{E} \times \vec{H}) - \frac{\partial}{\partial t} \left( \frac{\epsilon \cdot \vec{E} \cdot \vec{E}}{2} + \frac{\mu \vec{H} \cdot \vec{H}}{2} \right)$$

$$\xleftrightarrow{\text{jemná záporná}} \left( \frac{\vec{D} \cdot \vec{E}}{2} + \frac{\vec{B} \cdot \vec{H}}{2} \right)$$

$$w = w_e + w_m$$

$\vec{S} \rightarrow$  Poyntingův vektor  $\rightarrow$  kolmý na  $\vec{E}$  a  $\vec{H}$

$$n = \vec{E} \cdot \vec{j} = -\text{div}(\vec{S}) - \frac{\partial w}{\partial t}$$

$$\text{vakuum: } j=0 \rightarrow \underline{\text{div } \vec{S} + \frac{\partial w}{\partial t} = 0}$$

"rovnice kontinuity"



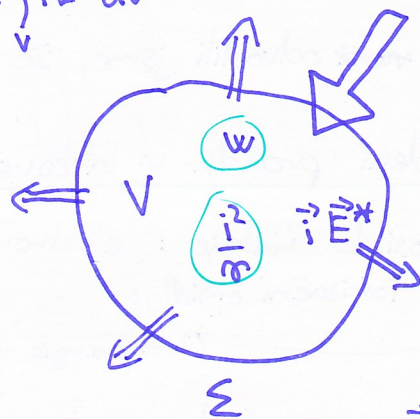
$$\vec{j} = \gamma (\vec{E} + \vec{E}^*) \quad \left| \frac{1}{\gamma} \right|$$

$$\left( \frac{j^2}{\gamma} \right) = \vec{j} \cdot \vec{E} + \vec{j} \cdot \vec{E}^*$$

hustota Joule. tepla

$$\frac{j^2}{\gamma} + \text{div} \vec{S} + \frac{\partial w}{\partial t} = \vec{j} \cdot \vec{E}^* \quad \left| \int_V \right.$$

$$\int_V \frac{j^2}{\gamma} dV + \underbrace{\int_V \text{div} \vec{S} dV}_{\int_{\Sigma} \vec{S} d\vec{S}} + \int_V \frac{\partial w}{\partial t} dV = \int_V \vec{j} \cdot \vec{E}^* dV$$



## Elektromagnetické vlny

$$\Delta f - \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2} = 0$$

Maxwellovy vce:  $\text{div} \vec{D} = \rho$   
 $\text{rot} \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t}$

$$\text{div} \vec{B} = 0$$

$$\text{rot} \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$\text{rot} \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$\text{rot} \text{rot} \vec{E} + \frac{\partial}{\partial t} (\text{rot} \vec{B}) = 0$$

$$-\Delta \vec{E} + \text{grad} \varphi (\text{div} \vec{E}) + \frac{\partial}{\partial t} (\mu_0 \vec{j} + \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t}) = 0$$

ve vakuu, prostě bez volných nábojů  
 $\rho = 0 \Rightarrow \text{div} \vec{E} = 0$

$$-\Delta \vec{E} + \mu_0 \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

nevodivé prostředí  $\vec{j} = 0$

$$\text{rot} \text{rot} \vec{B} = \mu_0 \epsilon \frac{\partial}{\partial t} (\text{rot} \vec{E})$$

$$-\Delta \vec{B} + \text{grad} (\text{div} \vec{B}) = -\mu_0 \epsilon \frac{\partial^2 \vec{B}}{\partial t^2}$$

$$\rightarrow \Delta \vec{B} - \mu_0 \epsilon \frac{\partial^2 \vec{B}}{\partial t^2} = 0$$

$$\underline{\underline{\vec{B}(\vec{r}, t)}}$$

$$\underline{\underline{\vec{E}(\vec{r}, t)}}$$

## Rovinná vlna

vlnoplocha

fázová rychlost

(frekvence)

periodicita

$\vec{B}$

$$\vec{B}(\vec{r} - \vec{v}t)$$

$$\vec{B}(t - \frac{\vec{r} \cdot \vec{v}}{v})$$

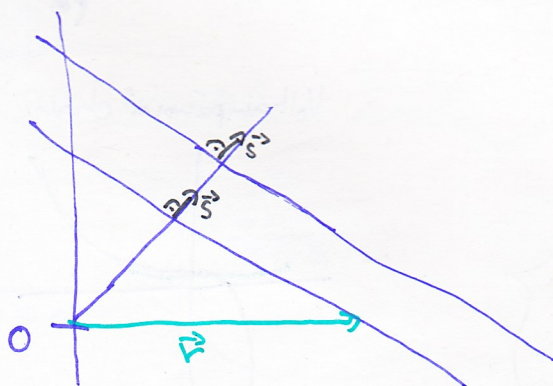
$$\vec{B}(\vec{r} \cdot \vec{s} - \frac{2\pi}{\lambda} v \cdot t)$$

$$\vec{B}(\vec{r} \cdot \vec{s} - \frac{2\pi}{T} \cdot t) ; \vec{B}(\vec{r} \cdot \vec{s} - \omega t)$$

$$F(\xi) = F(\xi + \eta)$$

perioda

vlnové číslo:  $k = \frac{2\pi}{\lambda}$



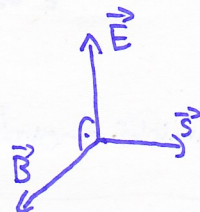
$$\vec{E}(t - \frac{\vec{r} \cdot \vec{v}}{v}) ; \vec{B}(t - \frac{\vec{r} \cdot \vec{v}}{v})$$

$$\frac{\partial \vec{E}}{\partial x} = -\frac{\partial \vec{E}}{\partial t} \frac{s_x}{v}$$

$$(\text{rot} \vec{E})_x = \frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} = -\frac{\partial E_z}{\partial t} \cdot \frac{s_y}{v} + \frac{\partial E_y}{\partial t} \cdot \frac{s_z}{v} = -\frac{1}{v} (\vec{s} \times \frac{\partial \vec{E}}{\partial t})_x$$

$$(\text{rot} \vec{E})_x = -\frac{\partial B_x}{\partial t} \Rightarrow \frac{\partial B}{\partial t} = \frac{1}{v} (\vec{s} \times \frac{\partial \vec{E}}{\partial t})$$

$$\frac{\partial}{\partial t} [\vec{B} - \frac{1}{v} (\vec{s} \times \vec{E})] = 0 \quad \underline{\underline{\vec{B} = \frac{1}{v} (\vec{s} \times \vec{E})}}$$





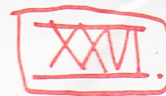
$\vec{B} = \mu_0 \vec{H}$  ;  $(\text{rot } \vec{B} = \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t})$

$\text{rot } \vec{B} = -\frac{1}{V} (\vec{S} \times \frac{\partial \vec{B}}{\partial t})$

$\frac{1}{V^2} \frac{\partial \vec{E}}{\partial t} = -\frac{1}{V} (\vec{S} \times \frac{\partial \vec{B}}{\partial t}) \implies \underline{\vec{E} = -V \cdot (\vec{S} \times \vec{B})}$

(polarizace světla)  
až v rámci optiky

$\Rightarrow$  ~~získali~~ odvodili jsme, že rovinná elmag. vlna je příčná.



## Vedení proudu v látkovém prostředí

nositelé náboje : elektrony, ionty

Plyny

ionizační činidlo:

$E \uparrow$   
0  $\rightarrow$  (energie volných elektronů)

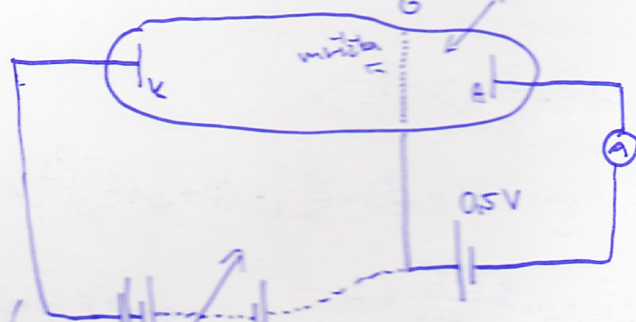
excitované stavy

základní stav

ionizační potenciál  
H<sub>a</sub> .... 13,6 eV  
He ..... ~22 eV

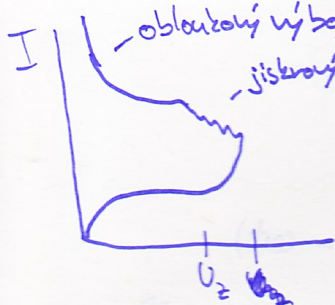
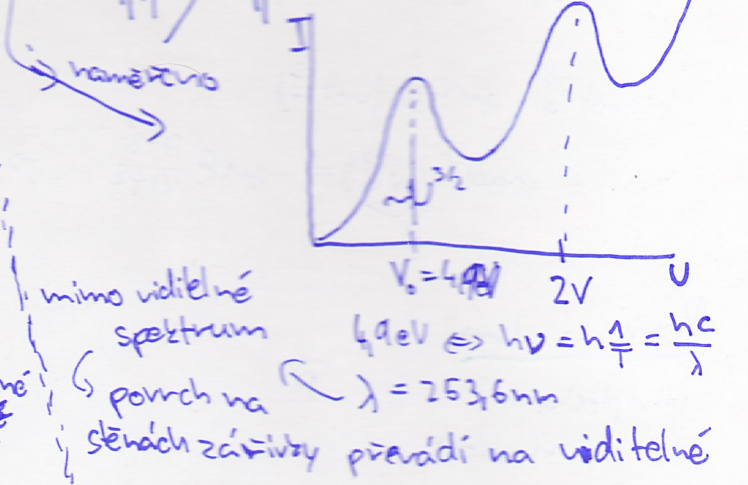
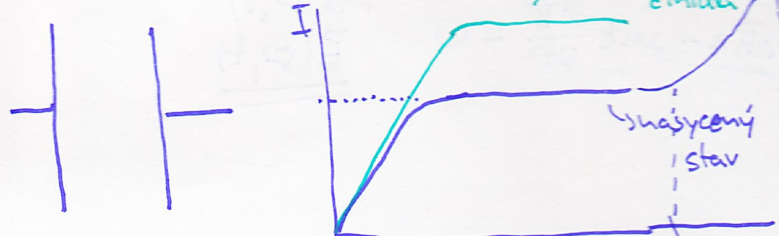
J. Franck, G. Hertz

přít. Hg



## Paschenův zákon

při větší intenzitě  
ionizačního činidla

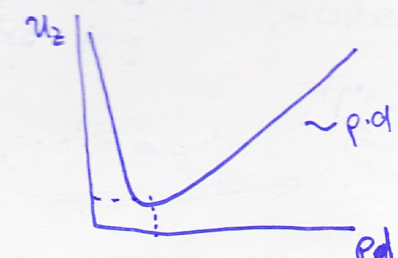


$U_z = f(p \cdot d)$

$\bar{I} \sim \frac{1}{p}$

$w_i = q \cdot E \cdot \bar{l} \Rightarrow w_i \sim g \cdot \frac{1}{p} \cdot \frac{U}{d}$

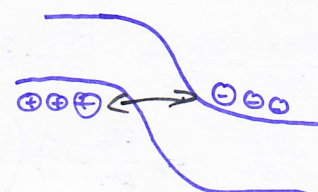
$U \propto \frac{w_i}{q} (p \cdot d)$



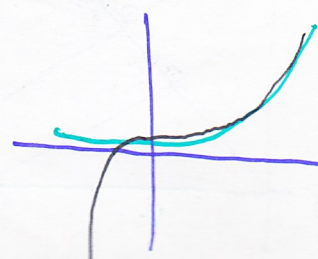
Ohmické chování

$\vec{J} = \mu \cdot \vec{E}$

veliký posun :

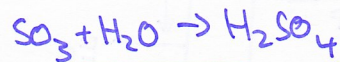
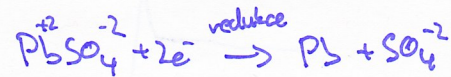


Voltampérová char. p.n. přech.





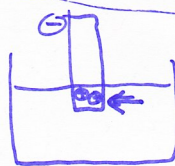
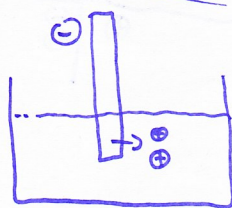
Ve kapalině → autobaterie



rozpuštěno

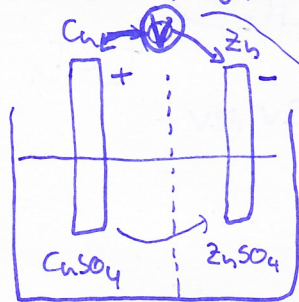
elektrolyt

disociace elektrolytu



polarizace

<del>Pt, Ag, Au, Hg, C, Fe</del>	Pt, Au, Hg, Ag, C, Cu	H	Pb, Fe, Zn, Al, Na, K
	1,6	0,3	-0,8



1,1 V

$$0,3 - (-0,8) \text{ V} = 1,1 \text{ V}$$

Danielův článek

elektrolýza

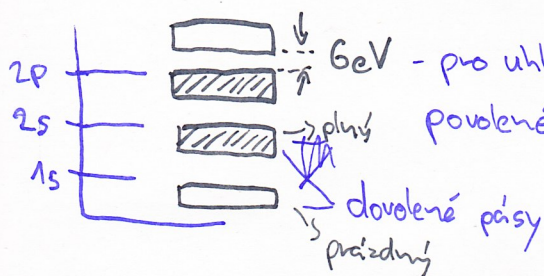
polarizace elektrod

polarizační elekt. napětí  $E_p$

Faradayovy zákony elektrolýzy → oprávit znalosti.

Vedení proudu v pevných látkách

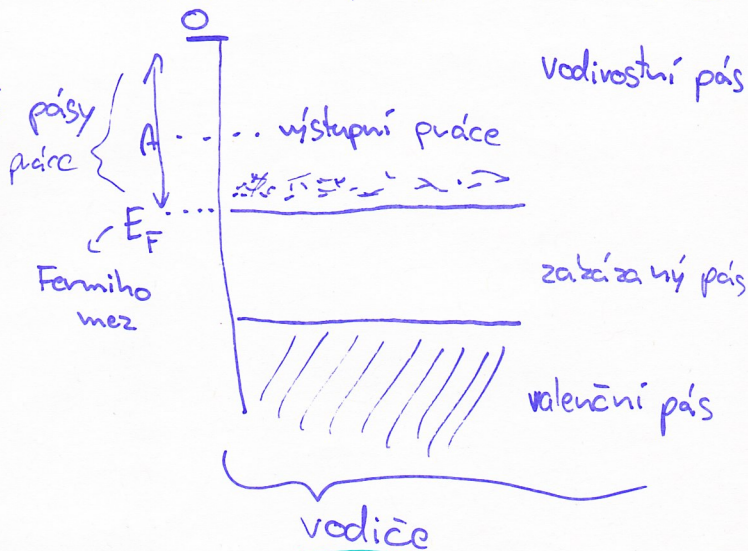
pásový model elektronové struktury → hladiny jsou v pevných látkách širší



6 eV - pro uhlík (diamant)

povolené a zakázané pásy

dovolené pásy  
prázdný



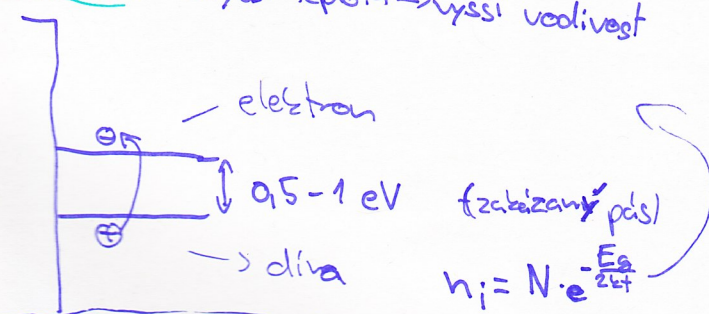
vodivostní pás

zakázaný pás

valenční pás

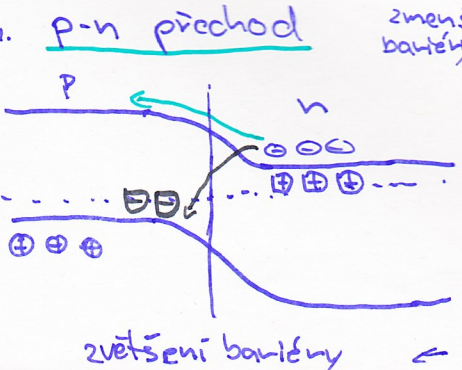
vodiče

Polovodiče → vyšší teplota → vyšší vodivost



$$n_i = N \cdot e^{-\frac{E_g}{2kT}}$$

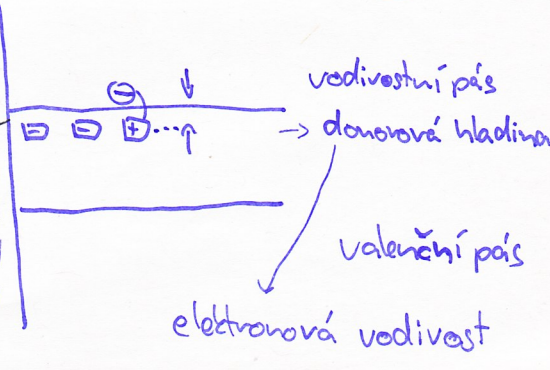
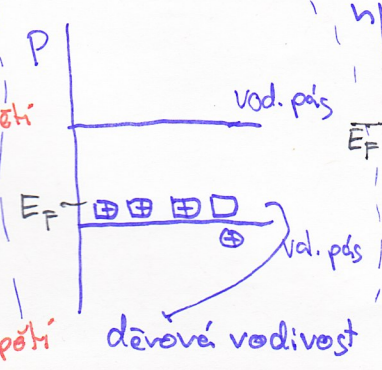
Neklasní polovodiče p, n



zmenšení bariéry

→ napětí

→ + napětí



vodivostní pás

→ donorová hladina

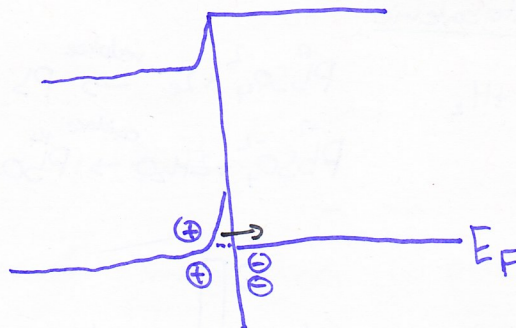
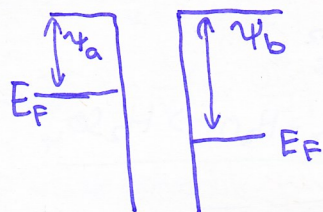
valenční pás

elektronová vodivost

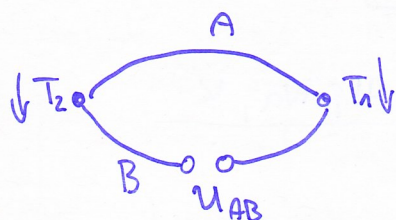
děrová vodivost



## Kontaktní potenciál

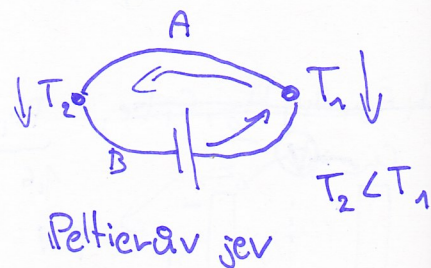


## Termočlánek



Seebeckův jev

$$U_{AB} \rightarrow \frac{U(T_2) - U(T_1)}{R}$$



Peltierův jev