

$$4) \quad \vec{B} = \nabla \times \vec{A} \quad \left| \quad \begin{aligned} \nabla \cdot \vec{B} &= 0 \\ \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \end{aligned} \quad \begin{aligned} \epsilon_0 \nabla \cdot \vec{E} &= \rho \\ \nabla \times \vec{B} &= \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \vec{j} \end{aligned}$$

+ Coulombova kalibrace:  $\nabla \cdot \vec{A} = 0$

a) rovnice pro  $\phi$ :

$$\left. \begin{aligned} \epsilon_0 \nabla \cdot \vec{E} &= \rho \\ \epsilon_0 \nabla \cdot \left( -\frac{\partial \vec{A}}{\partial t} - \nabla \phi \right) &= \rho \\ -\epsilon_0 \left( \frac{\partial}{\partial t} \underbrace{\nabla \cdot \vec{A}}_{=0 \text{ kalibrace}} + \Delta \phi \right) &= \rho \end{aligned} \right\} \quad \boxed{\Delta \phi = -\frac{\rho}{\epsilon_0}} \quad \dots \text{Poissonova rovnice}$$

b) rovnice pro  $\vec{A}$

$$\begin{aligned} \nabla \times \vec{B} - \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} &= \mu_0 \vec{j} \\ \nabla \times \nabla \times \vec{A} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left( \frac{\partial \vec{A}}{\partial t} + \nabla \phi \right) &= \mu_0 \vec{j} \\ -\Delta \vec{A} + \nabla(\nabla \cdot \vec{A}) + \mu_0 \epsilon_0 \frac{\partial^2 \vec{A}}{\partial t^2} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \nabla \phi &= \mu_0 \vec{j} \\ &= 0 \text{ kalibrace} \quad \int d\vec{r}' \frac{\rho(\vec{r}', t)}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|} \end{aligned}$$

$$\boxed{\Delta \vec{A} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{A}}{\partial t^2} = \mu_0 \vec{j} - \mu_0 \epsilon_0 \nabla \int d\vec{r}' \frac{\frac{\partial}{\partial t} \rho(\vec{r}', t)}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|}}$$

5)  $E_x(\vec{r}, t) = E_x(t) \cos(k_x x) \sin(k_y y) \sin(k_z z)$  + bez nabojů  
 $E_y(\vec{r}, t) = E_y(t) \sin(k_x x) \cos(k_y y) \sin(k_z z)$   
 $E_z(\vec{r}, t) = E_z(t) \sin(k_x x) \sin(k_y y) \cos(k_z z)$

a) dk, je  $\vec{k} \cdot \vec{E}(t) = 0$

Maxwellova rovnice  $\epsilon_0 \nabla \cdot \vec{E} = \rho \rightarrow$  bez nabojů:  $\nabla \cdot \vec{E} = 0$

$$\begin{aligned} \rightarrow \nabla \cdot \vec{E}(\vec{r}, t) &= -E_x(t) k_x \sin(k_x x) \sin(k_y y) \sin(k_z z) - E_y(t) k_y \sin(k_x x) \cos(k_y y) \sin(k_z z) - \\ &- E_z(t) k_z \sin(k_x x) \sin(k_y y) \cos(k_z z) = \vec{E}(t) \cdot \vec{k} \underbrace{\sin(k_x x) \sin(k_y y) \sin(k_z z)}_{\neq 0 \text{ identicky}} = 0 \\ \Rightarrow \boxed{\vec{E}(t) \cdot \vec{k} = 0} \quad \blacksquare \end{aligned}$$

b) určit  $\vec{E}(t)$

$$\left. \begin{aligned} \nabla \times \vec{B} - \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} &= \mu_0 \vec{J} \\ \nabla \times \vec{E} - \frac{\partial \vec{B}}{\partial t} &= 0 \end{aligned} \right\} \begin{aligned} \nabla_x (\nabla_x \vec{E}) + \frac{\partial}{\partial t} \nabla_x \vec{B} &= 0 \\ -\Delta \vec{E} + \nabla(\nabla \cdot \vec{E}) + \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} + \mu_0 \frac{\partial \vec{J}}{\partial t} &= 0 \end{aligned}$$

→ předpokládáme izotropní a homogenní prostředí bez proudů ⇒ dostáváme vlnovou rovnici:

$$\Delta \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$(\Delta \vec{E}(\vec{r}, t))_x = - \cancel{k_x^2} E_x(t) \cos(k_x x) \sin(k_y y) \sin(k_z z) \underbrace{(k_x^2 + k_y^2 + k_z^2)}_{|\vec{k}|^2}$$

+ analogicky pro další složky

→ v x-složce máme:

$$-k^2 E_x(t) \cos(k_x x) \sin(k_y y) \sin(k_z z) - \mu_0 \epsilon_0 \frac{\partial^2 E(t)}{\partial t^2} \cdot \cos(k_x x) \sin(k_y y) \sin(k_z z) = 0$$

$$\ddot{E}(t) + \underbrace{\frac{k^2}{\mu_0 \epsilon_0}}_{\omega^2} E(t) = 0 \dots \text{ODR 2. řádu} \rightarrow \text{hledáme řešení jako } e^{\alpha t}$$

$$\alpha^2 + \omega^2 = 0 \rightarrow \alpha = \pm i\omega \dots \text{rovnice trigonometrický systém}$$

$$\Rightarrow \left. \begin{aligned} E_x(t) &= E_x \sin(\omega t + \varphi_x) \\ E_y(t) &= E_y \sin(\omega t + \varphi_y) \\ E_z(t) &= E_z \sin(\omega t + \varphi_z) \end{aligned} \right|$$

c) určit magnetické složky pole

$$E_x(t) = E_x \sin(\omega t + \varphi_x) \cos(k_x x) \sin(k_y y) \sin(k_z z) \text{ atd. pro další složky}$$

$$\begin{aligned} \rightarrow (\nabla \times \vec{E})_x &= -\frac{\partial B_x}{\partial t} = E_z k_y \sin(\omega t + \varphi_z) \sin(k_x x) \cos(k_y y) \cos(k_z z) - \\ & E_y k_z \sin(\omega t + \varphi_y) \sin(k_x x) \cos(k_y y) \cos(k_z z) = \\ & = [E_z k_y \sin(\omega t + \varphi_z) - E_y k_z \sin(\omega t + \varphi_y)] \sin(k_x x) \cos(k_y y) \cos(k_z z) \end{aligned}$$

$$B_x = -\sin(k_x x) \cos(k_y y) \cos(k_z z) \int [E_z k_y \sin(\omega t + \varphi_z) - E_y k_z \sin(\omega t + \varphi_y)] dt$$

$$B_x = \left[ E_y \frac{k_y}{\omega} \cos(\omega t + \varphi_y) - E_z \frac{k_z}{\omega} \cos(\omega t + \varphi_z) \right] \sin(k_x x) \cos(k_y y) \cos(k_z z)$$

$$B_y = \left[ E_z \frac{k_z}{\omega} \cos(\omega t + \varphi_z) - E_x \frac{k_x}{\omega} \cos(\omega t + \varphi_x) \right] \cos(k_x x) \sin(k_y y) \cos(k_z z)$$

$$B_z = \left[ E_x \frac{k_x}{\omega} \cos(\omega t + \varphi_x) - E_y \frac{k_y}{\omega} \cos(\omega t + \varphi_y) \right] \cos(k_x x) \cos(k_y y) \sin(k_z z)$$

... analogicky i pro ostatni složky

6)  $D_k, \vec{e}$ :

$$\sum_{\lambda=1,2} \vec{e}_{\lambda, \vec{q}}^{\omega} \vec{e}_{\lambda, \vec{q}}^{\omega} = \delta^{\mu\nu} - \frac{\vec{q}^{\mu} \vec{q}^{\nu}}{q^2}, \text{ pokud } \vec{q} \cdot \vec{e}_{\lambda, \vec{q}} = 0.$$

$$\sum_{\lambda=1,2} \vec{e}_{\lambda, \vec{q}}^{\omega} \vec{e}_{\lambda, \vec{q}}^{\omega} = \delta^{\mu\nu} - \frac{\vec{q}^{\mu} \vec{q}^{\nu}}{q^2} \quad / \cdot q^{\mu}$$

$$\underbrace{\sum_{\lambda=1,2} \vec{e}_{\lambda, \vec{q}}^{\omega} q^{\mu} \vec{e}_{\lambda, \vec{q}}^{\omega}}_0 = \delta^{\mu\nu} q^{\mu} - \frac{q^{\mu} q^{\mu} q^{\nu}}{q^2}$$

$$= q^{\nu} - \frac{q^2 q^{\nu}}{q^2}$$

$$0 = q^{\nu} - q^{\nu} = 0$$

$$0 = 0. \quad \blacksquare$$